

Contact-based Metrics and Performance Implications in Mobile Ad-hoc Networks



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Disclaimer

- Collaboration with Han Cai, a PhD student at NCSU
- This talk is based on our recent two papers in
 - [1] Han Cai and Do Young Eun, “Crossing Over the Bounded Domain: From Exponential to Power-law Inter-meeting Time in MANET,” in **ACM MobiCom’07**, Montreal, Canada, Sept. 2007 (**Best Student Paper Award**)
 - [2] Han Cai and Do Young Eun, “Stochastic Anatomy of Inter-meeting Time Distribution under General Mobility Models,” in **ACM MobiHoc’08**, Hong Kong SAR, China, May 2008
- Papers and more details available at <http://www4.ncsu.edu/~dyeun>



Content

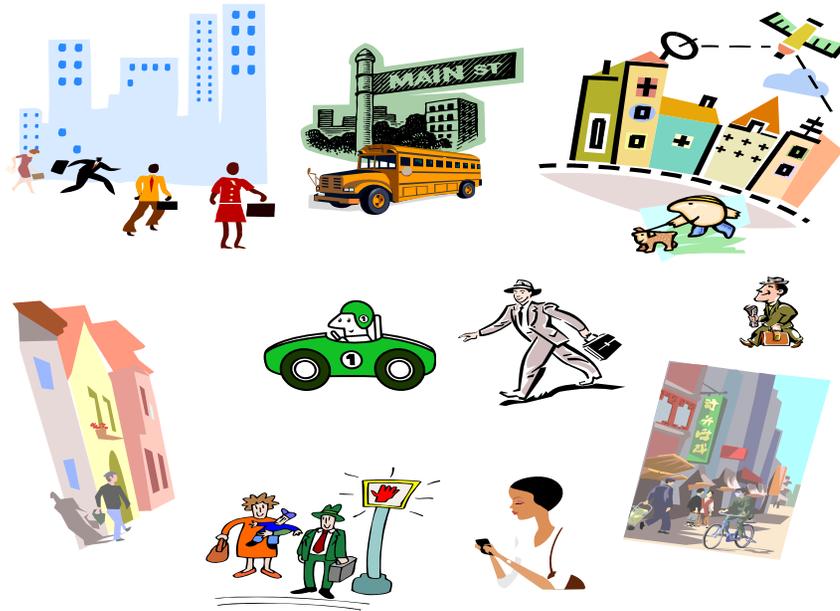
■ Introduction

- **Background: MANET, mobility models, contact-based metrics**
- Motivation

- Crossing over the bounded domain: From exponential to power-law inter-meeting time
- Stochastic anatomy of the inter-meeting time under general mobility models
- Performance implications and outlook



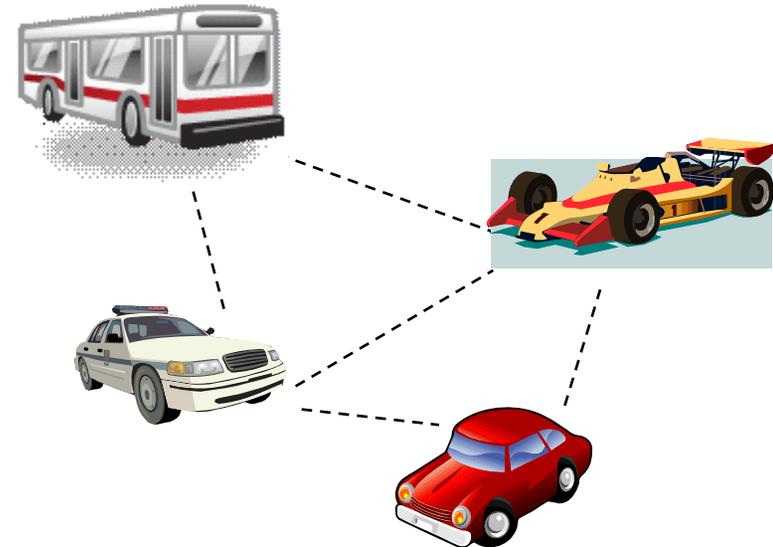
Mobile Ad-hoc Network (1)



- A type of self-configuring wireless ad-hoc network
 - Mobile nodes
 - Wireless communication devices



Mobile Ad-hoc Network (2)



■ Pocket Switch Network [1]

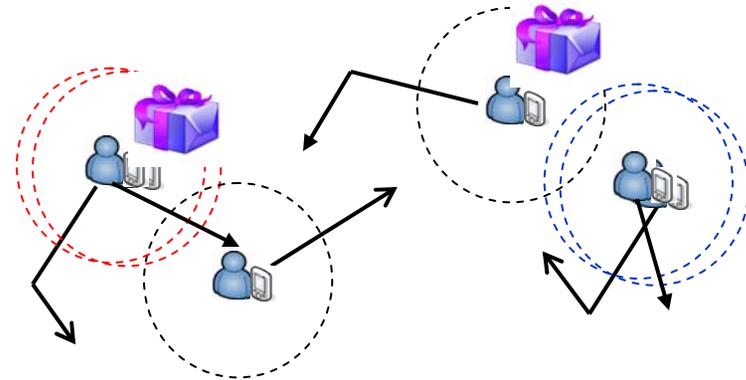
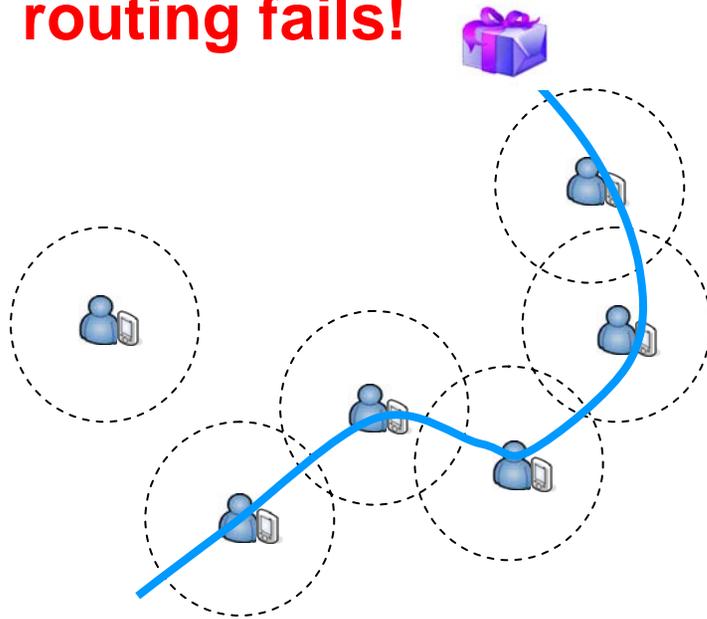
■ Vehicle Ad-hoc Network [2]

- [1] A. Chaintreau, P. Hui, J. Crowcroft, C. Diot, R. Gass, and J. Scott, “Impact of human mobility on the design of opportunistic forwarding algorithms,” in *IEEE INFOCOM*, Barcelona, SPAIN, 2006.
- [2] John Burgess, Brian Gallagher, David Jensen, and Brian Neil Levine, “Maxprop: Routing for vehicle-based disruption-tolerant networks”, in *IEEE INFOCOM*, Barcelona, SPAIN, August 2006.



Mobile Ad-hoc Network (3)

Intermittently connected – conventional path-based routing fails!

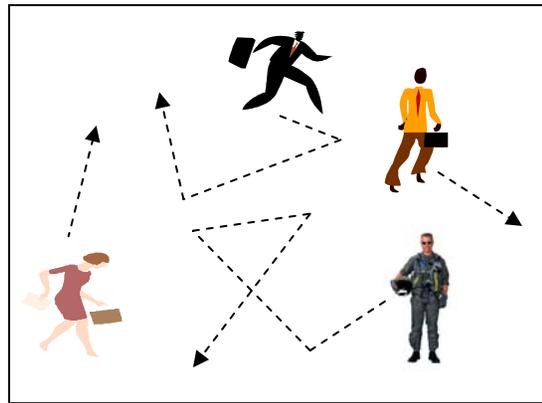


- Low mobility compared to packet transmission session
- High density ensures path existence

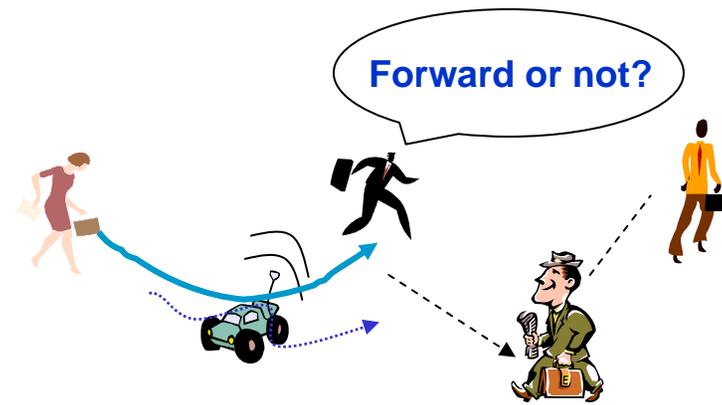
- **Low density:** conventional path fails
- **High mobility** compared to packet transmission session



Mobility, Forwarding, Performance



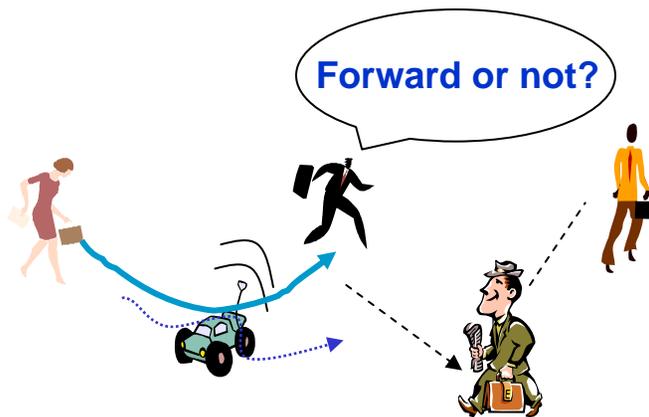
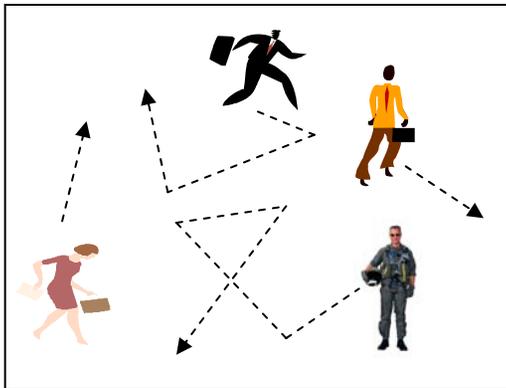
Random Mobility Pattern



Forwarding Strategy



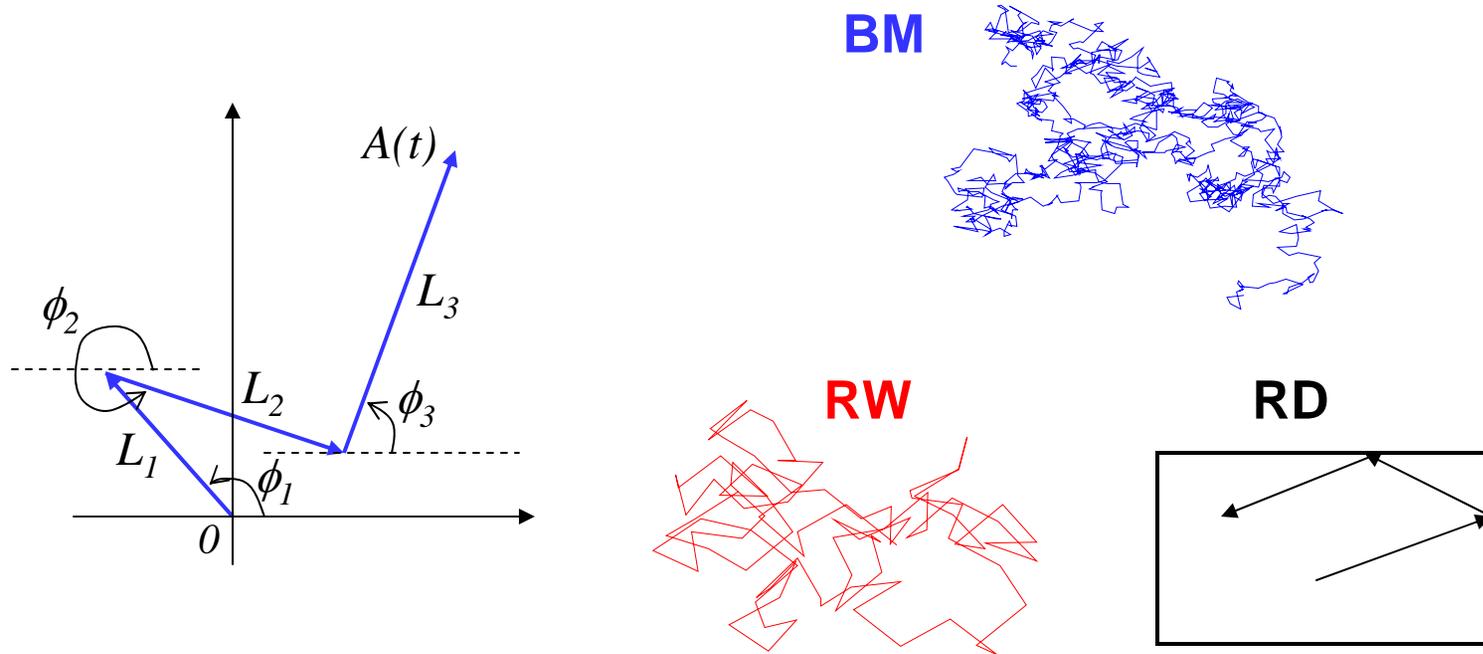
Mobility, Forwarding, Performance



- Capacity
- Delay
- # of copies/pkt
-



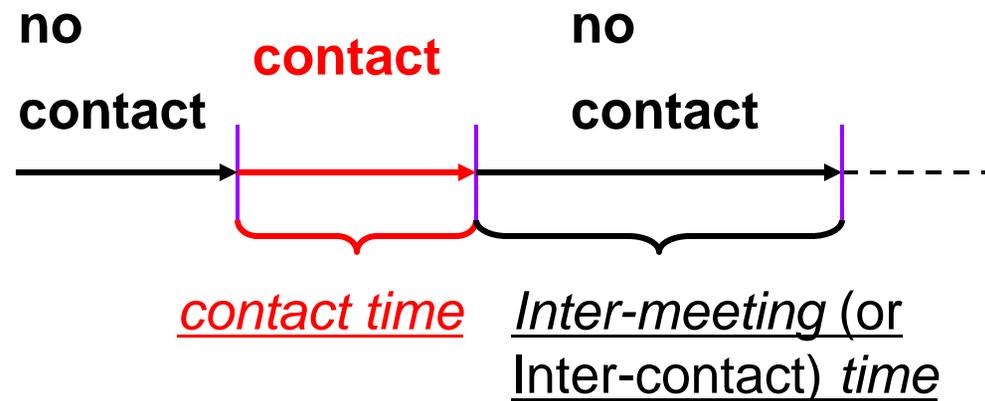
Mobility: Isotropic Random Walk model



- Isotropic Random Walk (IRW) models: BM, RW, RD, etc.
 - Angle: uniform
 - Step length: constant, exponential, uniform, etc.



Mobility-Induced Metrics



- Effect of mobility model on system performance → through mobility-induced metrics
 - Contact time, inter-meeting (or inter-contact) time, etc.
- F. Bai, N. Sadagopan, and A. Helmy, “Important: A framework to systematically analyze the impact of mobility on performance of routing protocols for ad-hoc networks,” in *IEEE INFOCOM* 2003.

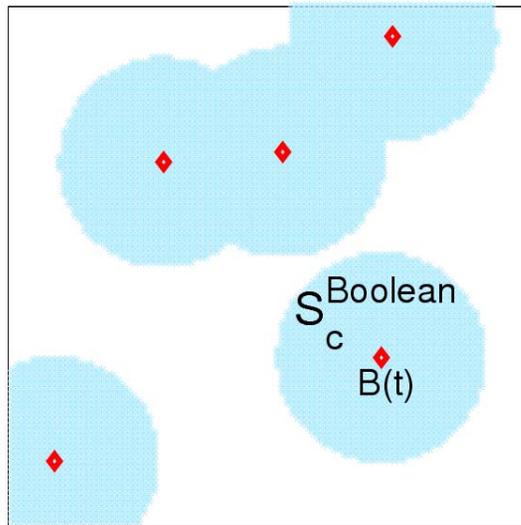


How to define “Contact”?

-- Interference Models

Boolean

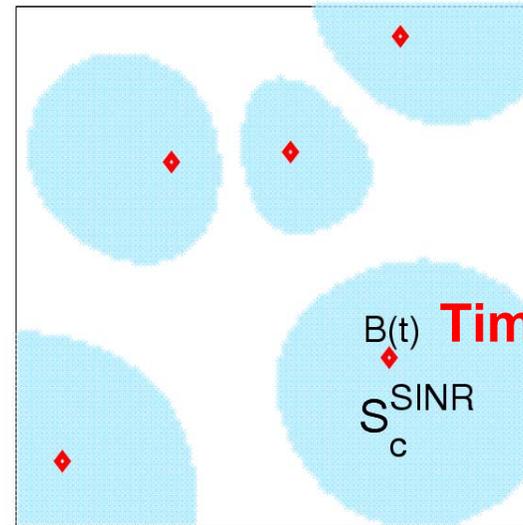
$$\|A(t) - B(t)\| \leq d$$



SINR

$$\frac{P_A \|A(t) - B(t)\|^\alpha}{N_0 + \sum_{i=1}^N P_i \|M_i(t) - B(t)\|^\alpha} \geq \gamma_0$$

Noise power level
min. SINR required



Time varying

■ Interference models: Distance-based; SINR based, etc.

- P. Gupta and P.R. Kumar, “The capacity of wireless networks,” *IEEE Transactions on Information Theory*, 2000.



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- Stochastic anatomy of the inter-meeting time under general mobility models
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Exponential Inter-meeting Time

■ Assumed for tractable analysis

$$\mathbb{P}\{T_I > t\} \sim e^{-ct}$$

- Delay-capacity tradeoff [1, 2]
- Forwarding algorithm performance analysis [3, 4]
- and many more....

■ Supported by

- Numerical simulations based on mobility model (RWP) [5]
- Theoretical result to upper bound first/second moment [6] using BM

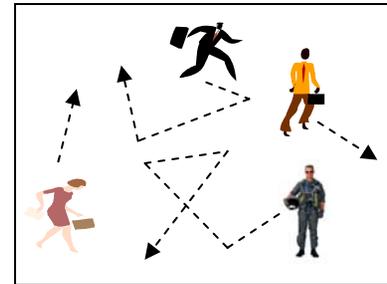
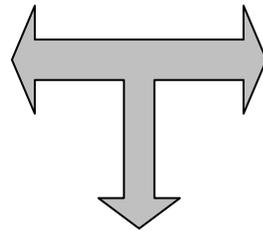
- [1] Grossglauser, M., and Tse, D. N. C. “Mobility increases the capacity of Ad Hoc wireless networks”, *IEEE/ACM Transactions on Networking*, 2002.
- [2] Sharma, G., Mazumdar, R., and Shroff, N. B., “Delay and Capacity Trade-offs in Mobile Ad Hoc Networks: A Global Perspective,” in *IEEE INFOCOM 2006*.
- [3] T. Spyropoulos, K. Psounis, and C. Raghavendra, “Efficient Routing in Intermittently Connected Mobile Networks: The Multi-Copy Case,” in *IEEE/ACM Transactions on Networking*, Feb. 2008.
- [4] X. Zhang, G. Neglia, J. Kurose, and D. Towsley, “Performance Modeling of Epidemic Routing,” *Computer Networks*, 2007.
- [5] Groenevelt, R., Nain, P., and Koole, G., “Message delay in MANET,” in *ACM SIGMETRICS*, 2004.
- [6] Sharma, G., and Mazumdar, R. “On achievable delay/capacity trade-offs in Mobile Ad Hoc Networks,” *WiOpt*, 2004.



Exponential Assumption: Enabler of “Everything”...

$$\mathbb{P}\{T_I > t\} \sim e^{-ct}$$

Exponentially distributed
Inter-meeting time of a pair



i.i.d. mobile
nodes

Poisson contact with rate λ among “all” mobile nodes

- Poisson contact across time and space
 - “Memoryless” → no need to “remember” when was the last time of contact
 - You are likely to meet anybody at any time instant “regardless” of the past experience
 - Only “current status” matters (# of nodes having the packet in question, etc)
- Heavily adopted in almost all theoretical work so far
 - Capacity-delay tradeoff in mobile ad-hoc networks
 - Markovian analysis of forwarding/routing algorithms



But ...

$$\mathbb{P}\{T_I > t\} \sim t^{-\alpha}$$

■ Recently discovered: Power-law [1, 2]

Effect of power-law on system performance [1]

“... If $\alpha < 1$, none of these algorithms, including flooding, can achieve a transmission delay with a finite expectation....”

- [1] A. Chaintreau, P. Hui, J. Crowcroft, C. Diot, R. Gass, and J. Scott, “Impact of human mobility on the design of opportunistic forwarding algorithms,” in *IEEE INFOCOM*, Barcelona, SPAIN, 2006.
- [2] Hui, P., Chaintreau, A., Scott, J., Gass, R., Crowcroft, J., and Diot, C., “Pocket switched networks and the consequences of human mobility in conference environments,” in *WDTN-05*.



Power-law Inter-meeting Time

Recent studies on power-law (selected)

■ Call for new mobility models [1]

- Use 1-D random walk model to produce power-law inter-meeting time [2]

■ Call for new forwarding algorithms [3]

- [1] A. Chaintreau, P. Hui, J. Crowcroft, C. Diot, R. Gass, and J. Scott, “Impact of human mobility on the design of opportunistic forwarding algorithms,” in *IEEE INFOCOM*, Barcelona, SPAIN, 2006.
- [2] Boudec, J. L., and Vojnovic, M. “Random Trip Tutorial,” in *ACM MobiCom Tutorial*, 2006.
- [3] Lindgren, A., Diot, C., and Scott, J. “Impact of communication infrastructure on forwarding in pocket switched networks,” in *SIGCOMM workshop on Challenged networks*, 2006



Our Work

Key questions:

- What's the fundamental reason for the exponential & power-law behavior?
- What's the effect of general mobility patterns on system performance when the inter-meeting time is not purely exponential?

We provide answers to these questions !!

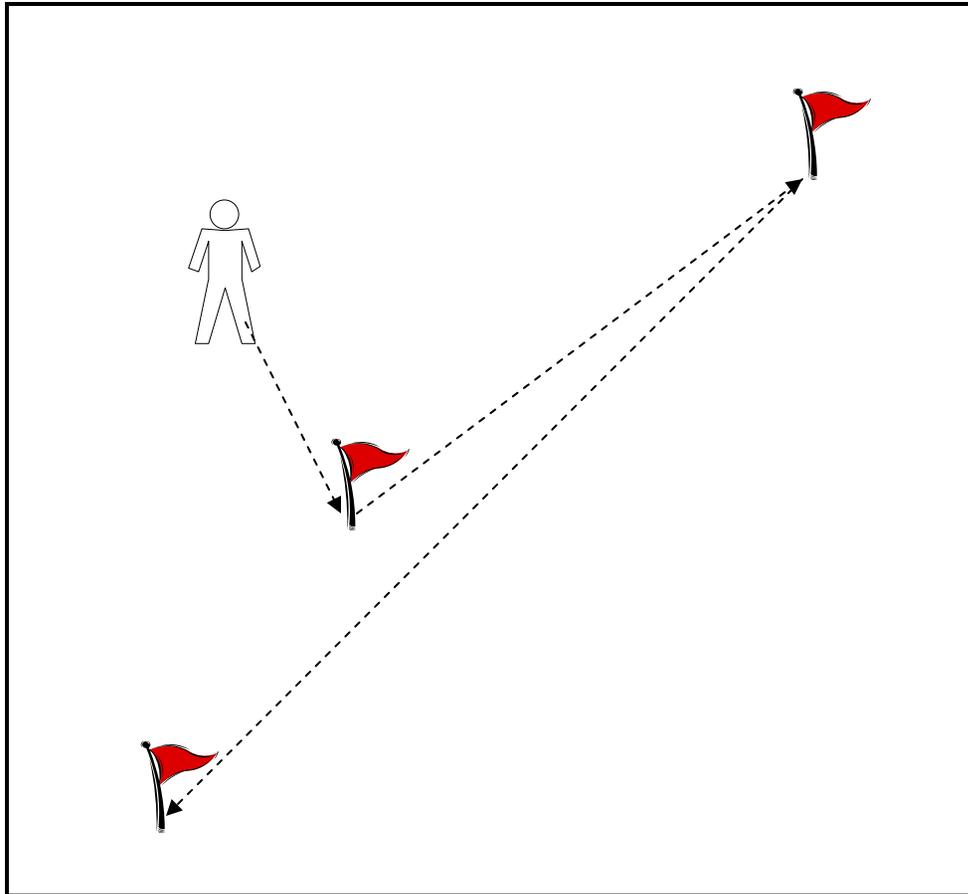


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Random WayPoint Model



■ RWP

- Zero pause time
- Random (light-tail) pause time
- Independent pair of nodes
- Boolean interference model



RWP with zero pause time

Proposition 1: Under zero pause time, there exists constant $c > 0$ such that

$$P\{T_I > t\} < e^{-ct},$$

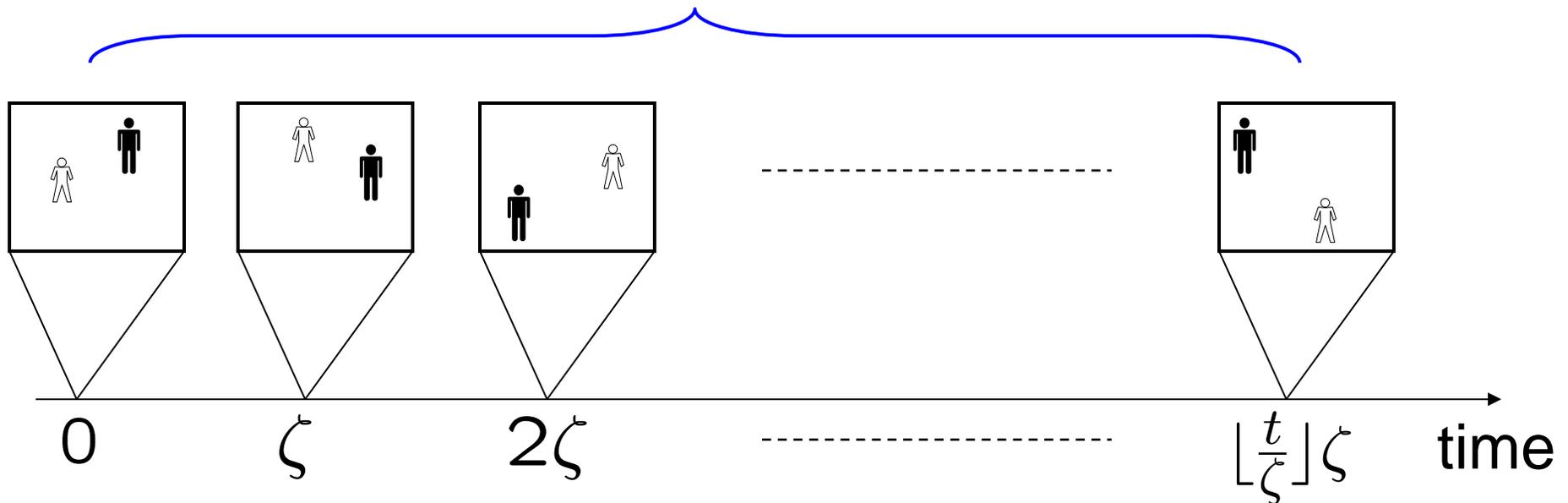
for all sufficiently large t .

- Proposition 1 is also true for “bounded” pause time case.



Proof sketch for Proposition 1

Independent “Images” (snapshot of node positions)



■ Over duration of $[0, t]$

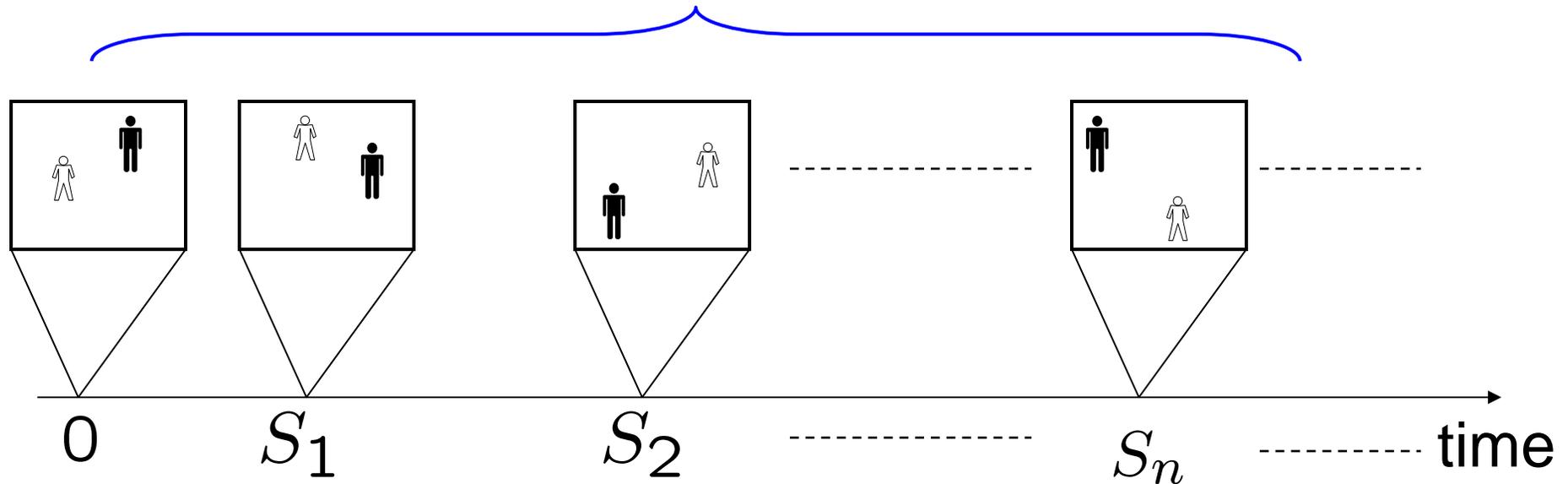
➤ # of independent “images” = $O(t)$

➤ Each “image”: $P \{ \text{not meeting} \} < c < 1$



Random Pause Time: Difficulty

Independent “Image”



- Possibly infinite pause time

- Impossible to get periodic independent images
- Can we still get $O(t)$ independent images?



RWP with random pause time

Theorem 1: Under random pause time, there exists constant $c > 0$ such that

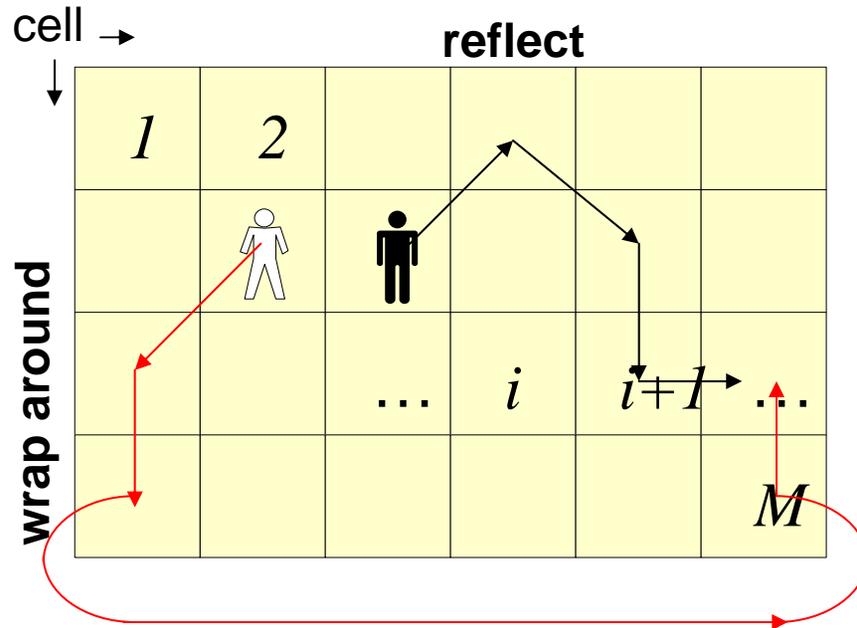
$$P\{T_I > t\} < e^{-ct},$$

for all sufficiently large t .

- Proposition 1 is extended to random pause time case, i.e., the pause time may be infinite.
 - Condition: the pause time has finite moments
- First formal proof for the exponential tail behavior of inter-meeting time CCDF



RWM: exponential inter-meeting



- Markov Chain RWM: transition matrix $P = \{p_{ij}\}$,

prob. of jumping from cell i to j

- Boundary behavior
 - Reflect
 - Wrap around

Theorem 2: Two independent nodes move according to the RWM. Then, there exists constant $\gamma > 0$ such that

$$P\{T_I > t\} \leq e^{-\gamma t},$$

for all sufficiently large t .

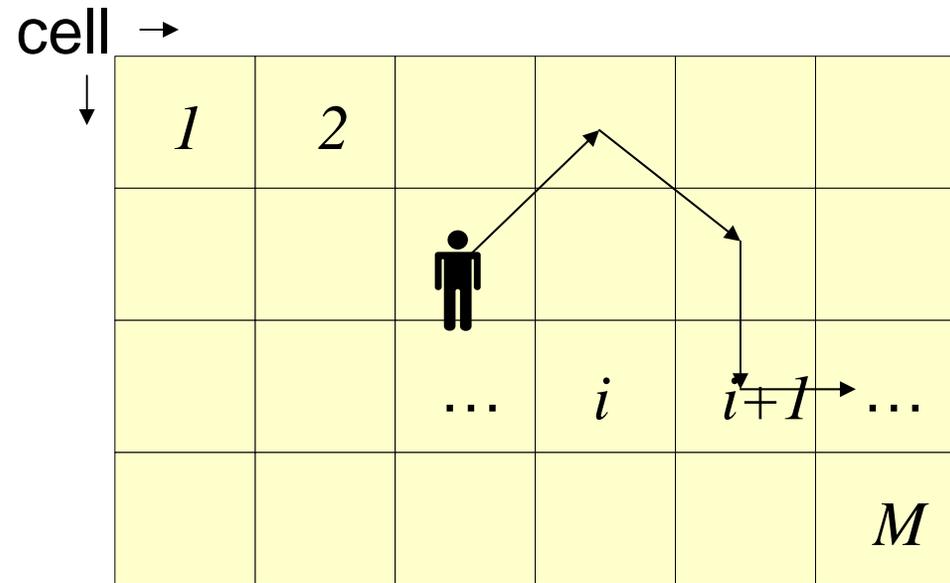
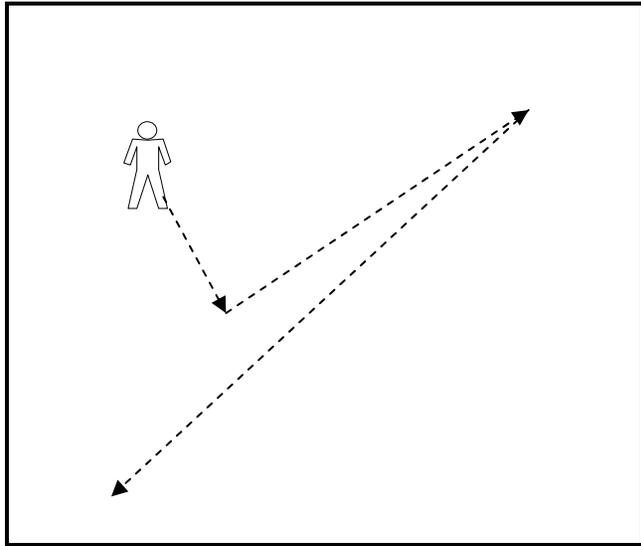


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Cause of Exponential Tail



What is common in all these models?



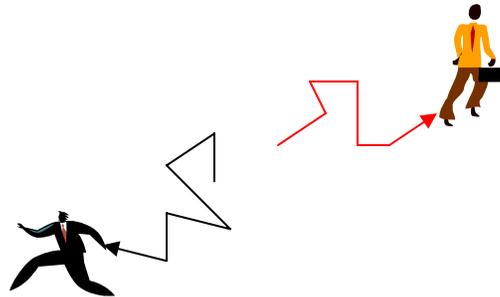
Cause of Exponential Tail

Finite Boundary!!!

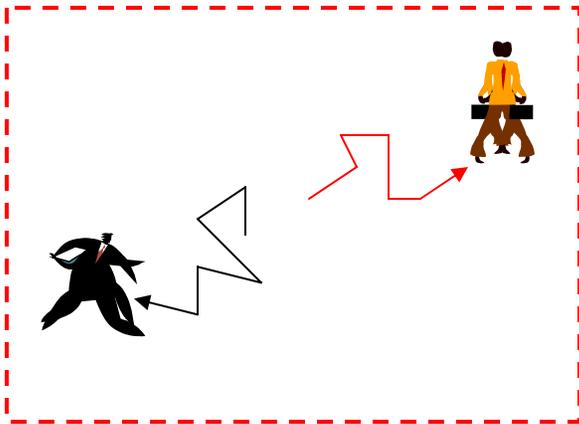
- **“Boundary”** is incorporated in the definition.
 - RWM: wrapping or reflecting **boundary behavior**
 - RWP: boundary concept inherited in model definition (destination for each jump is uniformly chosen from a **bounded domain**)
 - Virtual boundary
 - Intention of returning back to some locations regularly
 - Intention of being with others (mobile groups)
 - $O(1)$ communication range on a finite domain = finite number of states \rightarrow key to the exponential tail



Finite Boundary: Exponential Tail



- Two nodes not meet for a long time
 - most likely move towards different directions
 - prolonged inter-meeting time**<strong memory>**

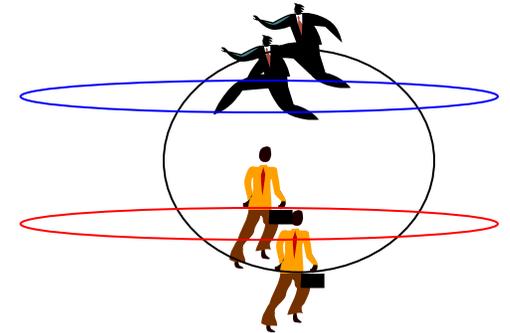


- Finite boundary erase this memory **<memoryless>**
 - resetting the memory in mobile trajectory



Other factors than the boundary?

- For most current synthetic models, finite boundary critically affects the “tail” behavior of inter-meeting time
- Other possible factors
 - Dependency between mobile nodes
 - Heavy-tailed pause time (with infinite mean)
 - Correlation in the trajectory of mobile nodes
- Our study focuses on:
 - Independence or weak-dependence case
 - Efficient generation of realistic mobility trajectories for simulation with matching statistical properties

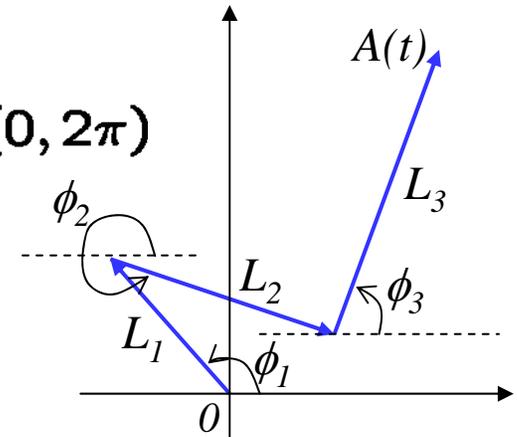




Removing the boundary ...

■ Discrete isotropic random walk in \mathbb{R}^2

- Choose a random direction uniformly from $[0, 2\pi)$
- Travel for a random length $L \in (0, \infty)$
- Repeat the above process



Theorem 3: Two independent nodes A, B move according to the 2-D isotropic random walk model described above. Then, there exists constant $C > 0$ such that the inter-meeting time T_I satisfies

$$P\{T_I > t\} \geq Ct^{-1/2},$$

for all sufficiently large t .



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Questions

About the boundary

- In reality, all domain under study is bounded
- In what sense does “infinite domain” exist?

About exponential / power-law behavior

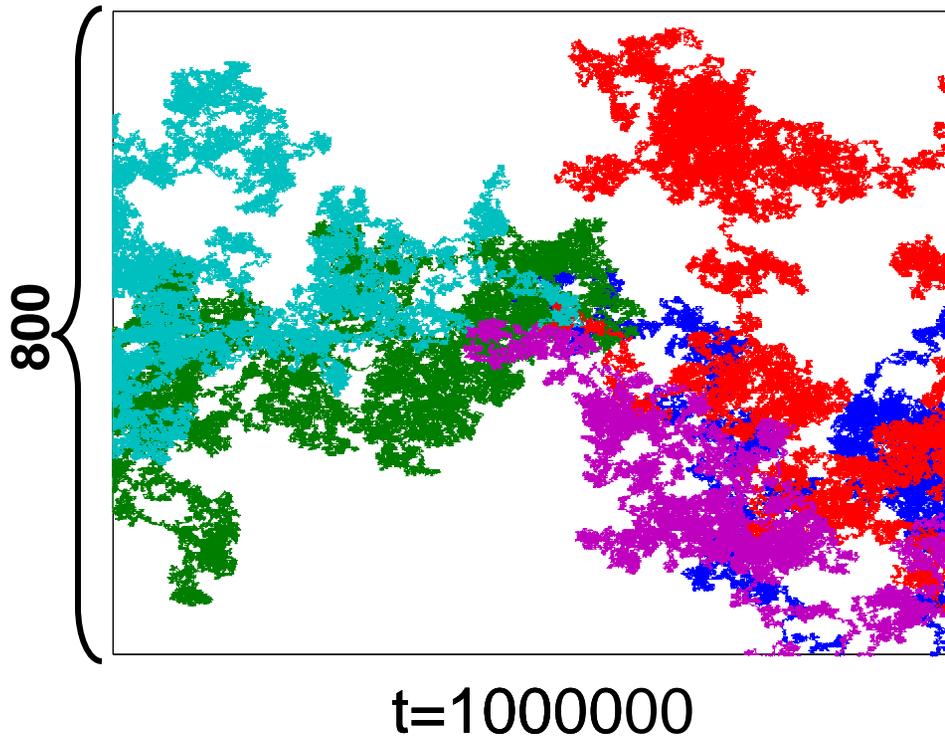
- “Where” does the transition from exponential to power-law take place?



Time / Space Scaling

- The **interaction** between the **timescale** under discussion and the **size** of the boundary

➤ Standard BM: position scale as $O(\sqrt{t})$



- Is 200X200 domain bounded?
 - **Unbounded** over time scale [0,100]
 - **Bounded** over time scale [0,1000000]
- **KEY:** whether the boundary effectively “erases” the memory of node’s movement



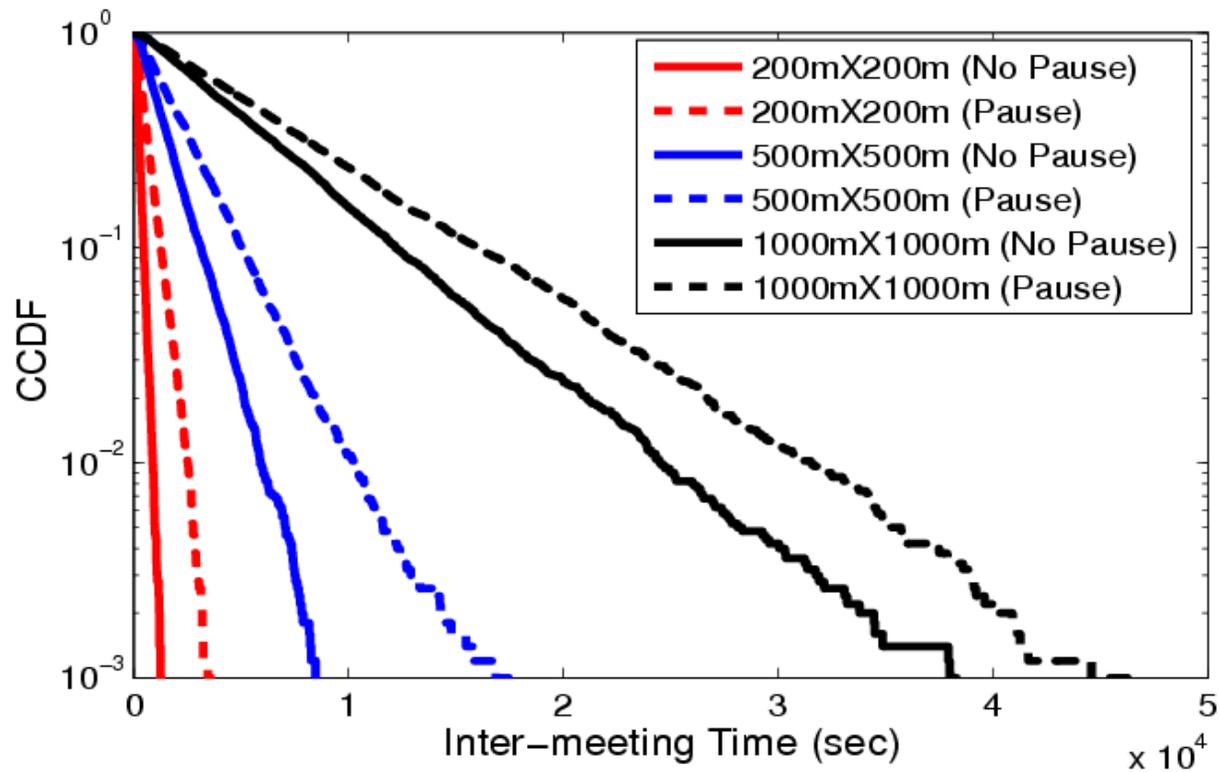
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RWP

Linear-Log

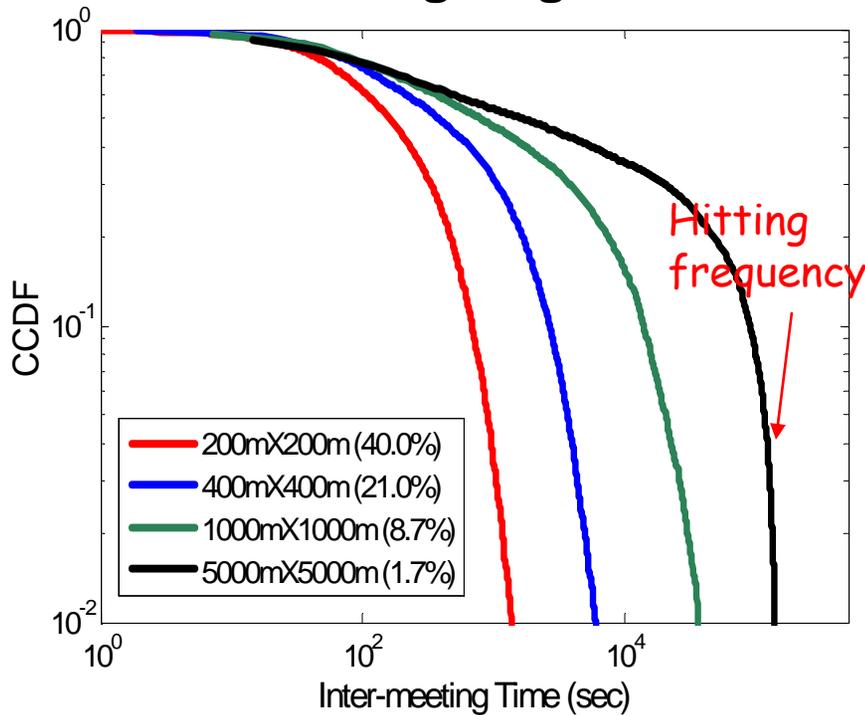


- Under given (fixed) domain: exponential behavior
 - Inherited memoryless property: resetting after two legs



RWM

Log-Log

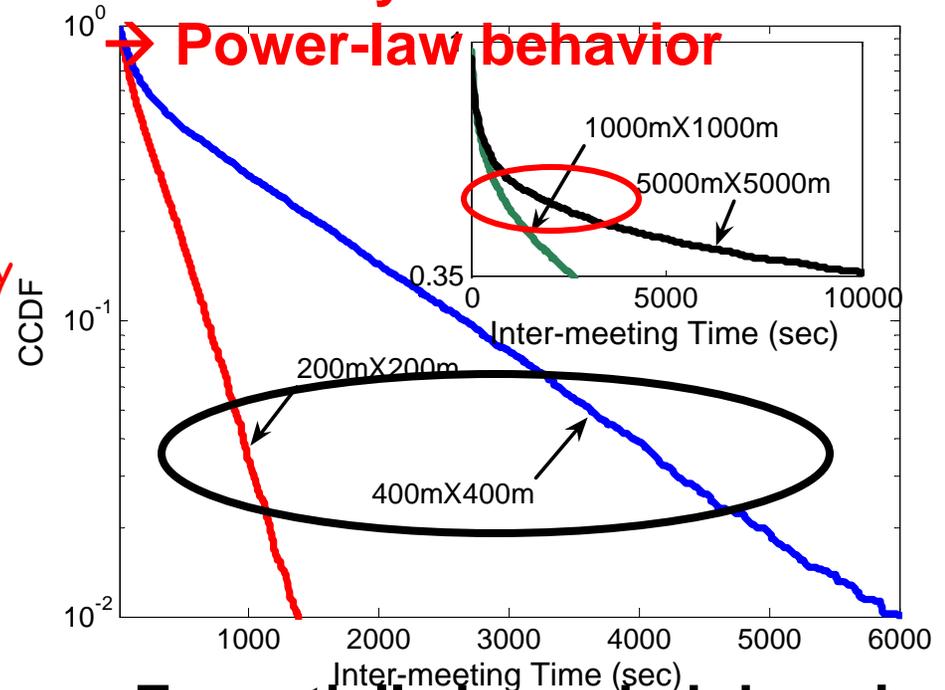


- RWM: change direction uniformly every 50 seconds
- Speed: $U(1.00, 1.68)$

Linear-Log

Essentially unbounded domain

→ Power-law behavior



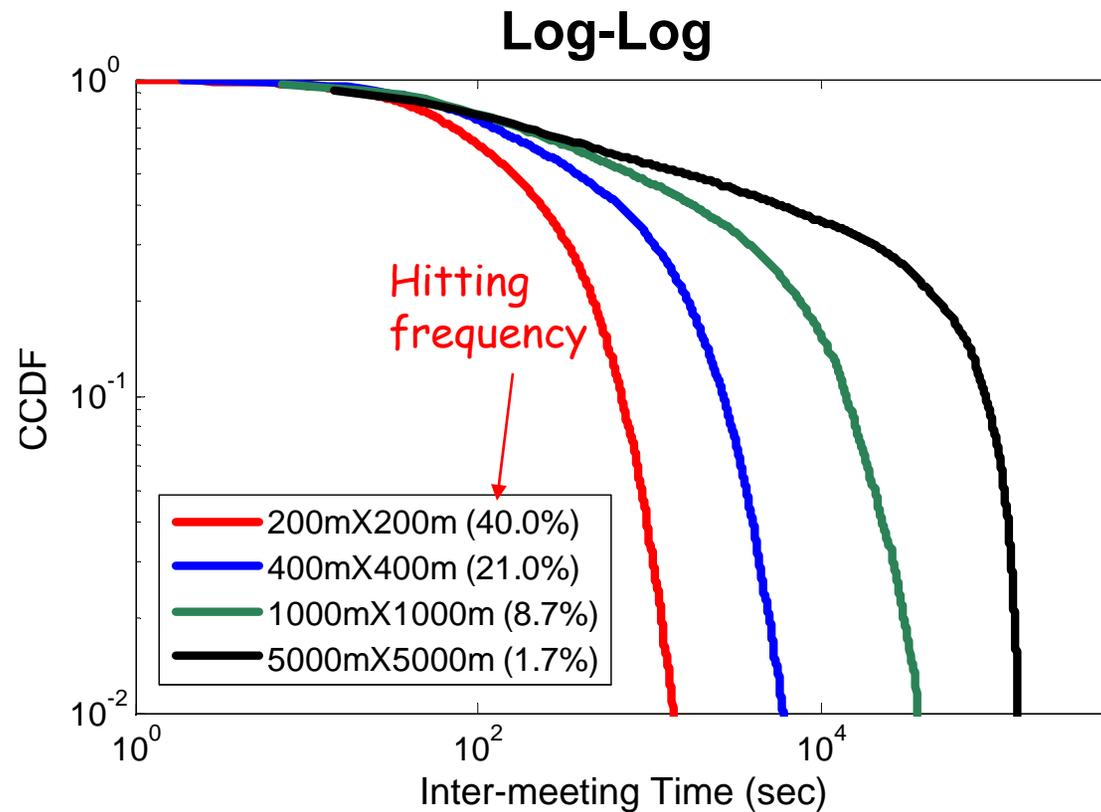
Essentially bounded domain

→ Exponential behavior

- Simulation period T : 40 hours



RWM



- RWM: change direction uniformly every 50 seconds
- Speed: $U(1.00, 1.68)$
- Simulation period T : 40 hours



Summary of Part I

- “**Finite boundary**” is a decisive factor for the tail behavior of inter-meeting time; we formally prove
 - The exponential tailed inter-meeting time based on RWP, RWM model
 - The power-law tailed inter-meeting time after removing the boundary
- **Time/space scaling**, i.e., the interaction between domain size and time scale under discussion is the key to understand the effect of boundary

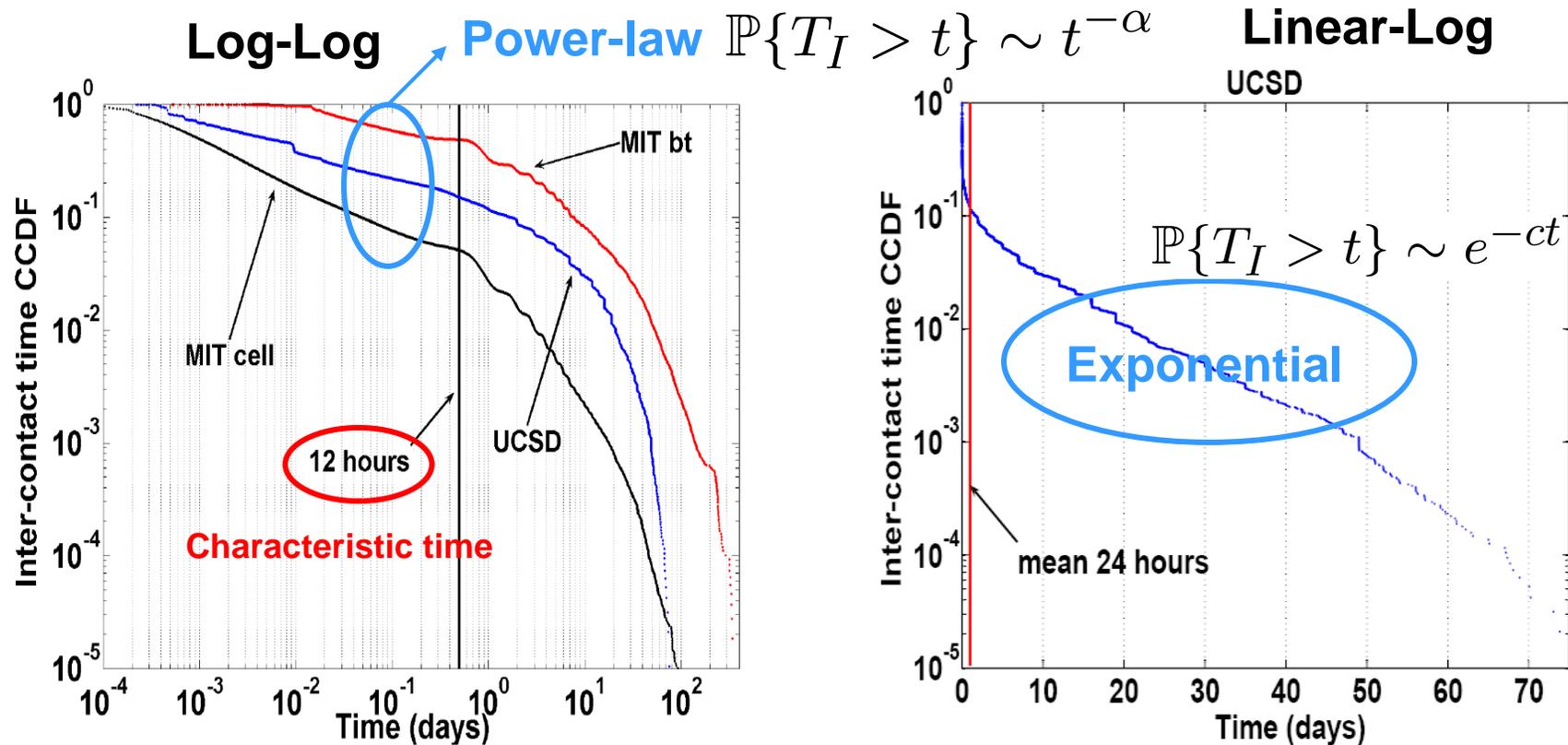


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- **Stochastic anatomy of the inter-meeting time under general mobility models**
 - **Head/Tail of Inter-meeting Time: A Closer Look at Dichotomy**
 - Stochastic Ordering for the Head of Inter-meeting Time
 - Invariance Property of Contact-based Metrics
- Performance implications and outlook



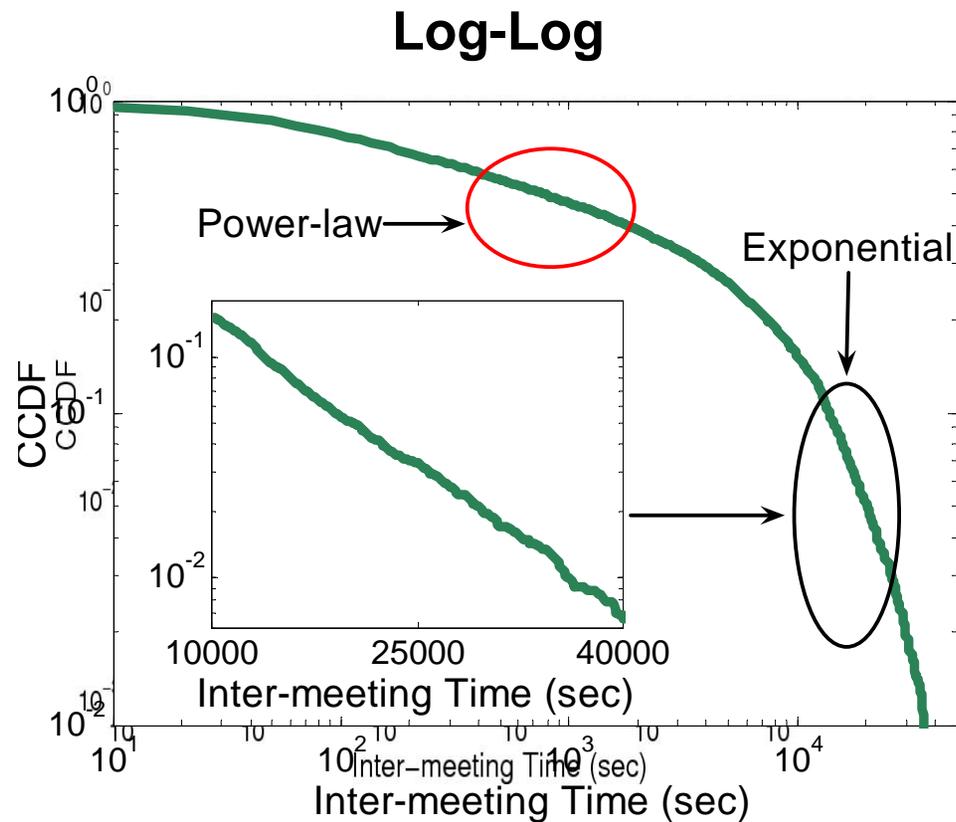
Mixture Behavior of Inter-meeting (1)



- T. Karagiannis, J.-Y. Le Boudec, and M. Vojnovic, “Power law and exponential decay of inter contact times between mobile devices,” in *ACM MobiCom*, Montreal, Canada, Sept. 2007



Mixture Behavior of Inter-meeting (2)



- Model: 2-D isotropic RW
- Domain: 1000m x 1000m
- Time scale vs. Domain size
 - Within 1000 seconds, essentially unbounded domain → power-law
 - After 10000 seconds, essentially bounded domain → exponential
- Physical/virtual boundary

- Han Cai and Do Young Eun, “Crossing Over the Bounded Domain: From Exponential to Power-law Inter-meeting Time in MANET,” in *ACM MobiCom*, Montreal, Canada, Sept. 2007 (**Best Student Paper Award**)



Mobility Model, Inter-meeting Time, and System Performance

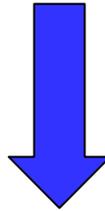


- Case 1: Exponential [1]
 - Average (or “rate”) is enough
 - Case 2: Power-law [2]
 - Heavy power-law inter-meeting → Infinite average delay
 - Case 3: Hyper-exponential [3]
 - Too complicated to provide intuitive guideline for design
 - No consideration on mobility models
-
- [1] Grossglauser, M., and Tse, D. N. C. “Mobility increases the capacity of Ad Hoc wireless networks,” in *IEEE/ACM Transactions on Networking*, 2002.
 - [2] A. Chaintreau, P. Hui, J. Crowcroft, C. Diot, R. Gass, and J. Scott, “Impact of human mobility on the design of opportunistic forwarding algorithms,” in *IEEE INFOCOM*, 2006.
 - [3] A. Al-Hanbali, A. A. Kherani, and P. Nain, “Simple models for the performance evaluation of a class of two-hop relay protocols,” in *IFIP Networking* 2007.

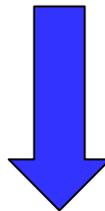


Mobility Model, Inter-meeting Time, and System Performance

General Mobility Models



Inter-meeting Time Distribution with Mixture Behavior

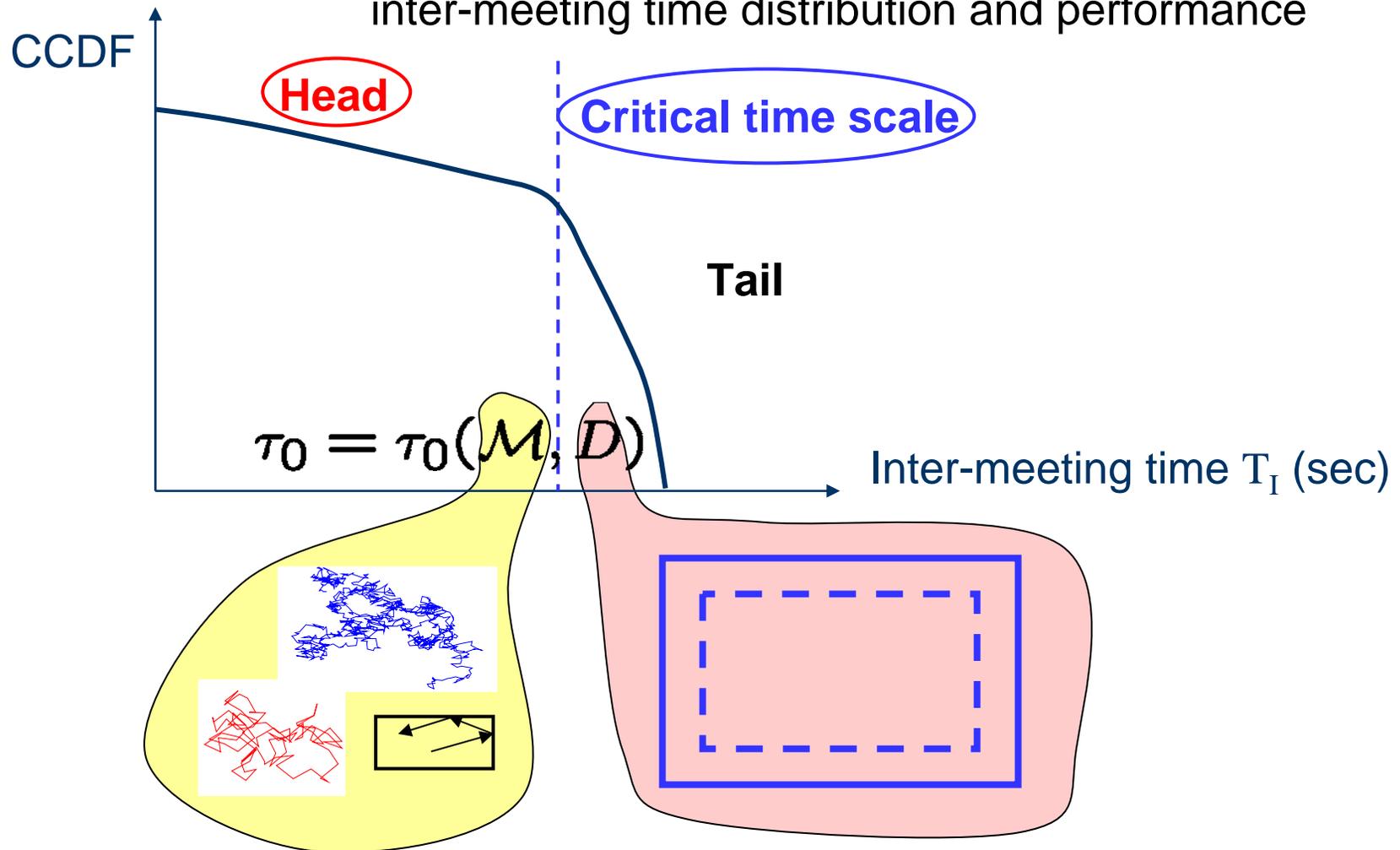


System Performance: capacity, delay, etc.



Stochastic Anatomy: Overview

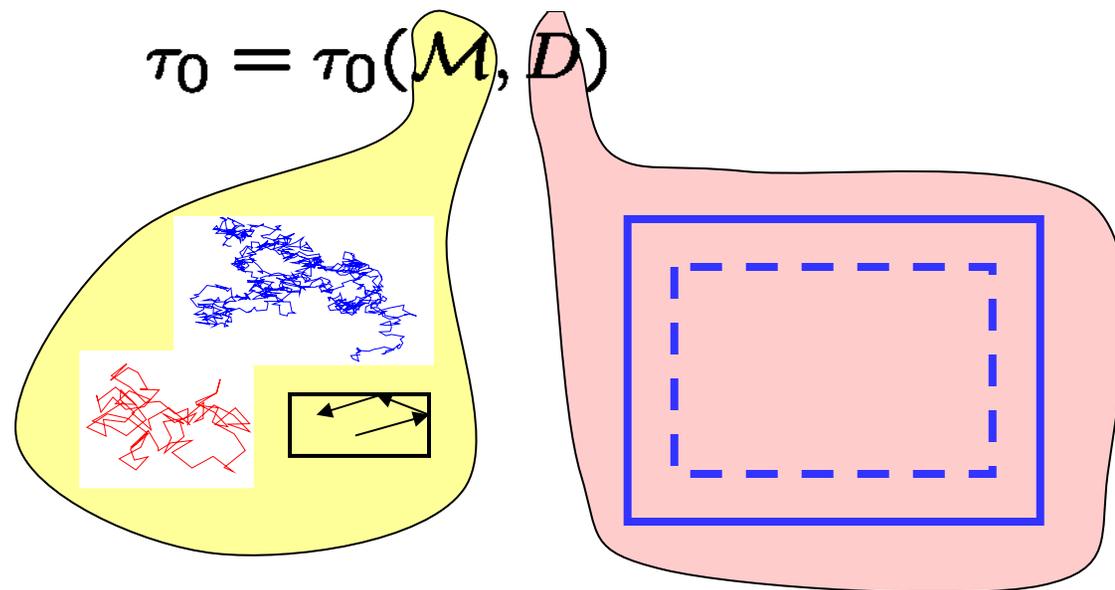
Effect of mobility model and domain size on inter-meeting time distribution and performance





Regenerative Period (Critical Time Scale)

- Regenerative period: Timescale beyond which the inter-meeting time becomes of exponential type (tail)



- [1] T. Karagiannis, J.-Y. Le Boudec, and M. Vojnovic, “Power law and exponential decay of inter contact times between mobile devices,” in *ACM MobiCom*, Montreal, Canada, Sept. 2007
- [2] Han Cai and Do Young Eun, “Crossing Over the Bounded Domain: From Exponential to Power-law Inter-meeting Time in MANET,” in *ACM MobiCom*, Montreal, Canada, Sept. 2007



Regenerative Period (Critical Time Scale)

- Regenerative period: Timescale beyond which the inter-meeting time becomes of exponential type (tail)

$$\tau_0 = \tau_0(\mathcal{M}, D)$$

- Similar to the characteristic time [1]
- Interaction between domain size and time scale [2]
 - Same order of the typical amount of time it takes for the node to travel D distance
 - Head ($t \ll \tau$): power-law; Tail ($t \gg \tau$): exponential
- [1] T. Karagiannis, J.-Y. Le Boudec, and M. Vojnovic, “Power law and exponential decay of inter contact times between mobile devices,” in *ACM MobiCom*, Montreal, Canada, Sept. 2007
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Effect of Boundary

$$\tau_0 = \tau_0(\mathcal{M}, D)$$

- Average displacement

$$\sigma(t) = \sqrt{\mathbb{E}\{|A(t)|^2\}}$$

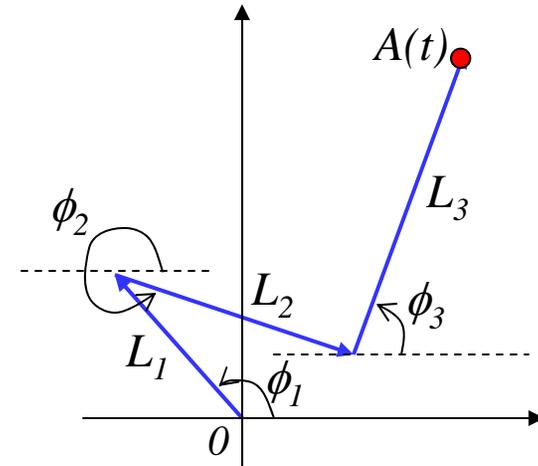
- For IRW: $\sigma(t) \sim \sqrt{t}$

- Relationship between τ_0 and D :

$$\sigma(\tau_0) = D \quad \tau_0 \propto D^2$$

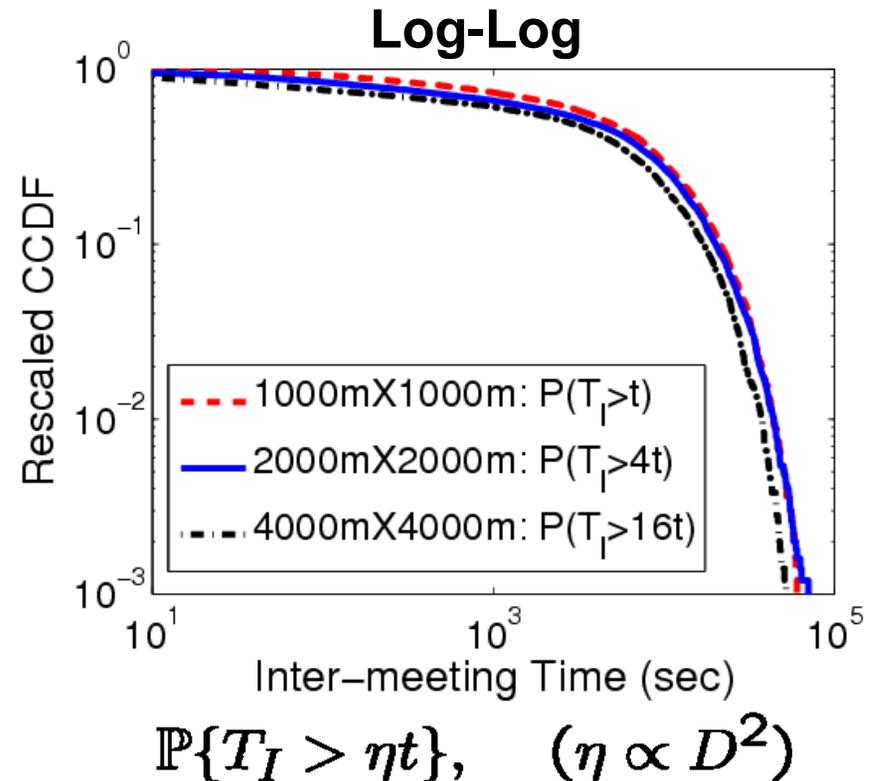
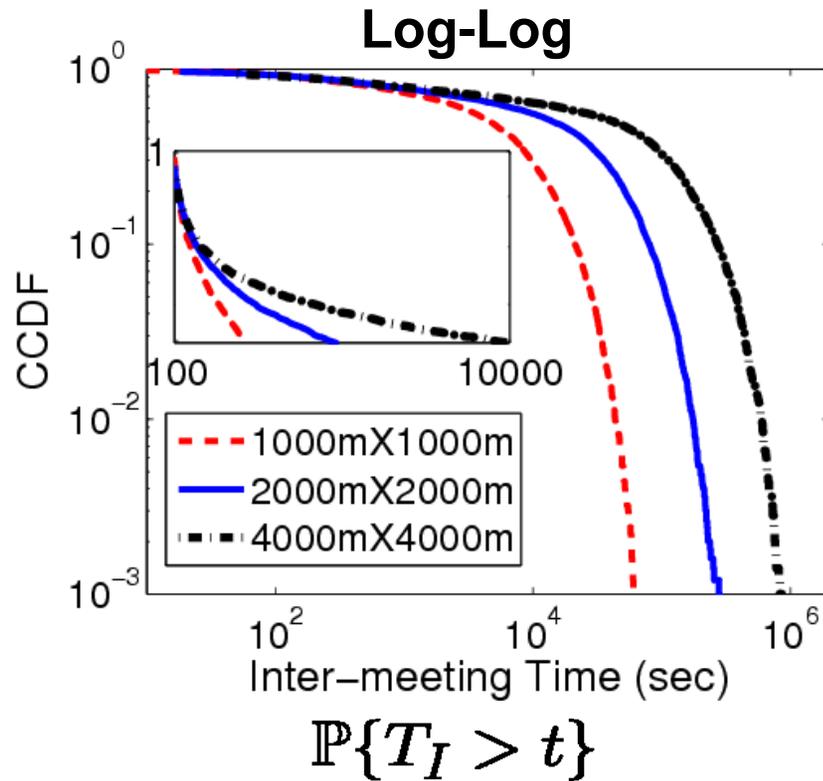
- Quantitatively observe this

scaling behavior $\mathbb{P}\{T_I > \eta t\}, \quad (\eta \propto D^2)$





Effect of Boundary $\tau_0 = \tau_0(\mathcal{M}, D)$ (2)

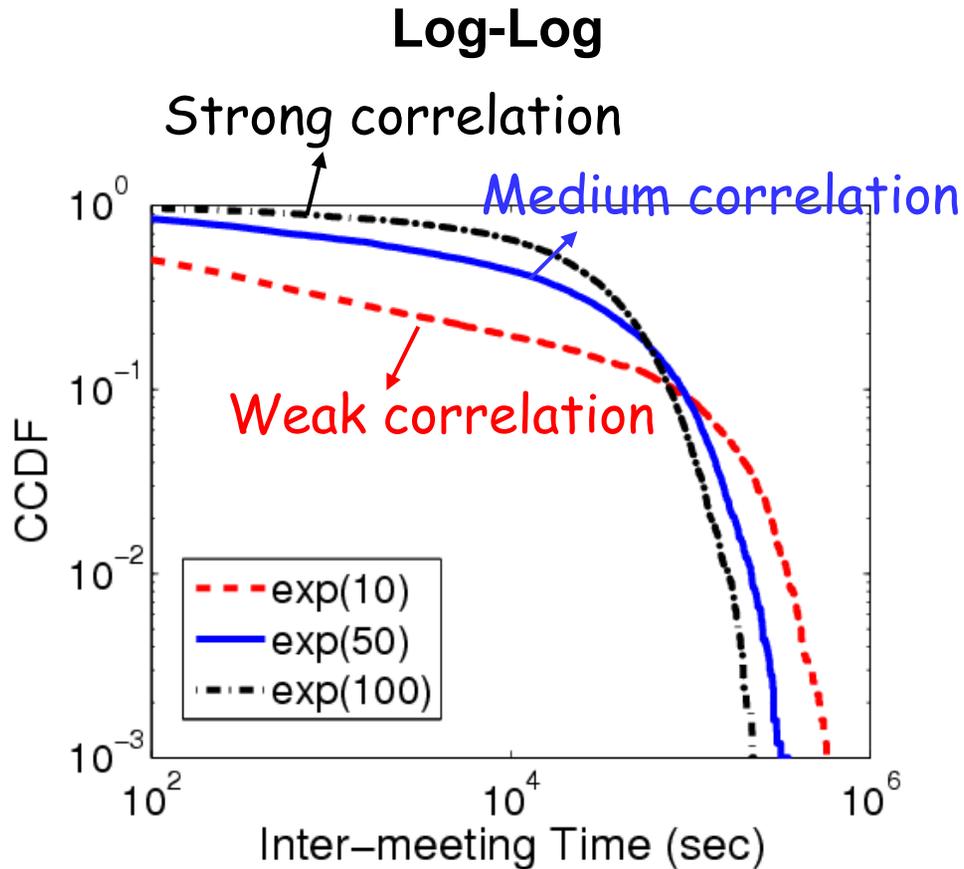


■ Effect of domain size on τ_0

➤ Step length: $\exp(100)$



Effect of Mobility Models: $\tau_0 = \tau_0(\mathcal{M}, D)$



■ Effect of 'correlation' of mobility models on τ_0

- Step length: exp(10), exp(50), exp(100).
 - Large average step length → stronger correlation
- Domain: 2000m x 2000m
- Stronger correlation in mobility pattern leads to smaller τ_0

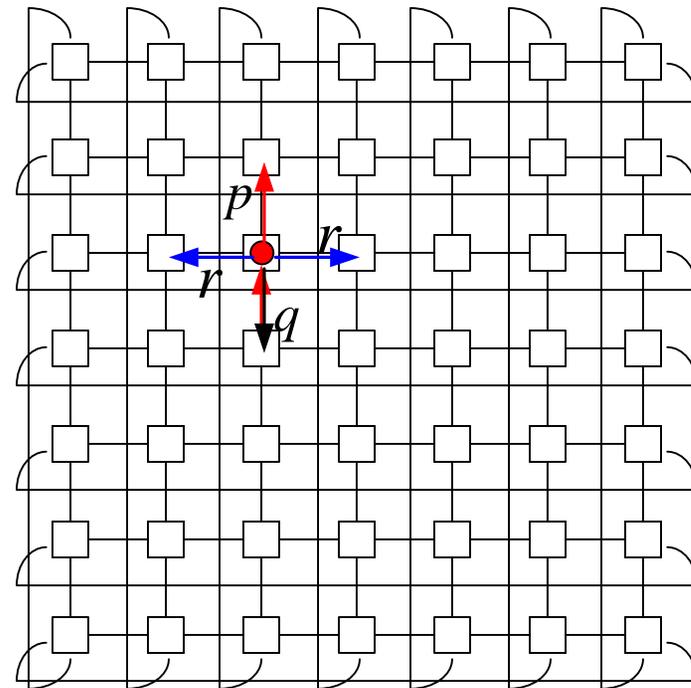
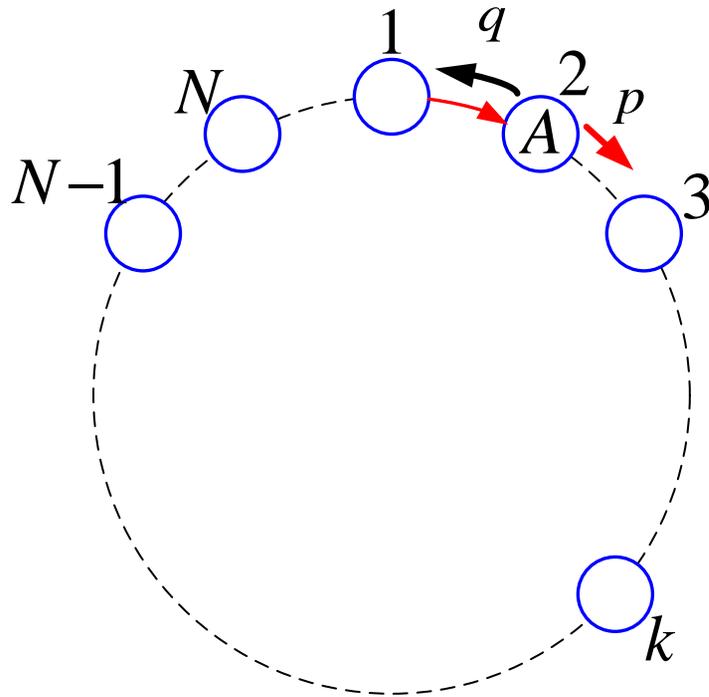


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- Crossing Over the Bounded Domain: from exponential to power-law inter-meeting time
- **Stochastic anatomy of the inter-meeting time under general mobility models**
 - Head/Tail of Inter-meeting Time: A Closer Look at Dichotomy
 - **Stochastic Ordering for the “Head” of Inter-meeting Time**
 - Invariance Property of Contact-based Metrics
- Performance implications and outlook

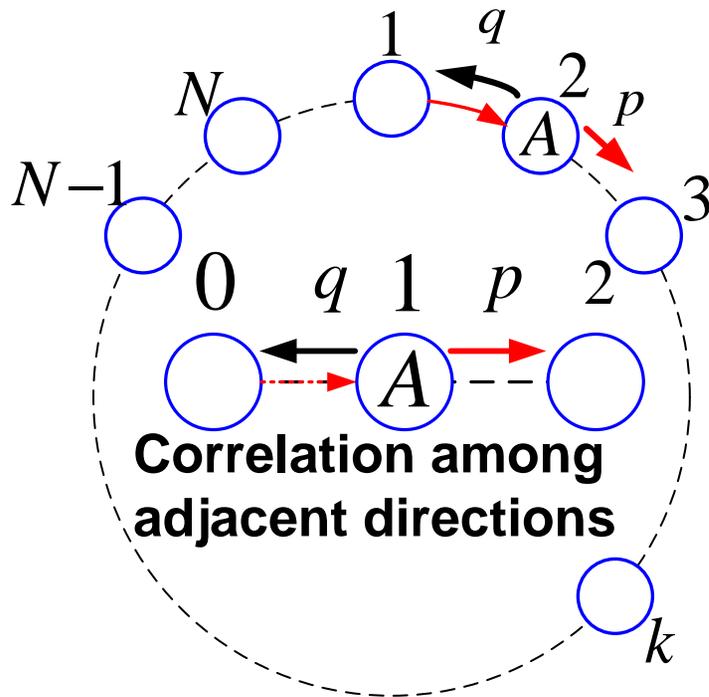


Correlated Random Walk (CRW)





Correlated Random Walk (CRW)



$p = \mathbb{P}\{\text{follow same direction}\}$
 $q = \mathbb{P}\{\text{follow opposite direction}\}$

$$p + q = 1$$

$$\rho = p - q$$

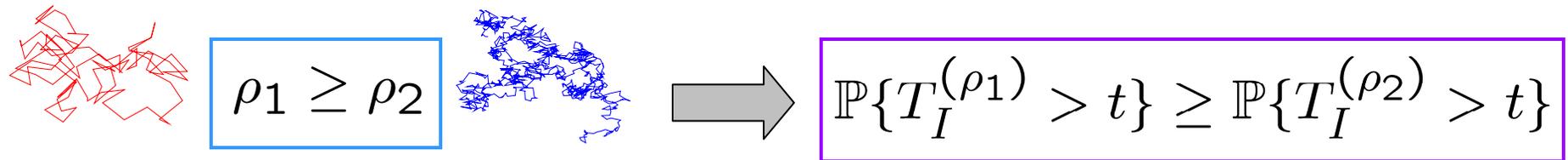
- Simple RW: $\rho = 0$; Bouncing: $\rho = -1$; Straight-line: $\rho = 1$
- `Head' of inter-meeting time:
 - Reside in an essentially unbounded domain: we let $N \rightarrow \infty$



Stochastic Ordering for T_I

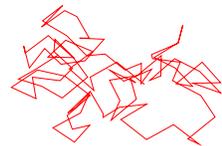
- Theorem 4:** Let T_I be the inter-hitting time of a mobile node C to the origin in an unbounded 1-D grid. Then, for any given $t > 0$, $\mathbb{P}\{T_I > t\}$ is an increasing function of $\rho \in [0, 1)$.

Correlation coefficient



Mobility pattern with ρ_1 has stronger correlation

$$T_I^{\rho_1} \geq_{st} T_I^{\rho_2}$$

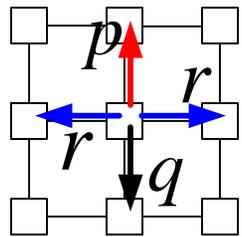


stronger correlation \rightarrow **heavier head** in the CCDF of the inter-meeting time

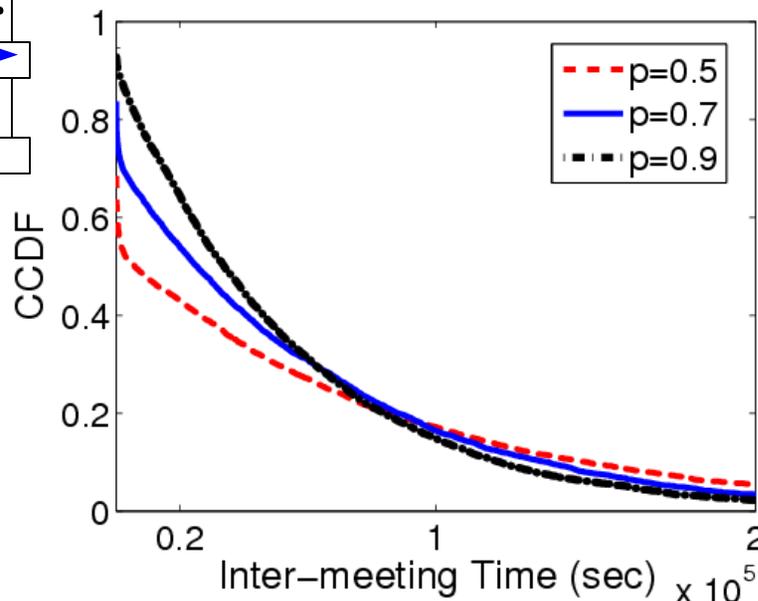


Extensions to 2-D CRW

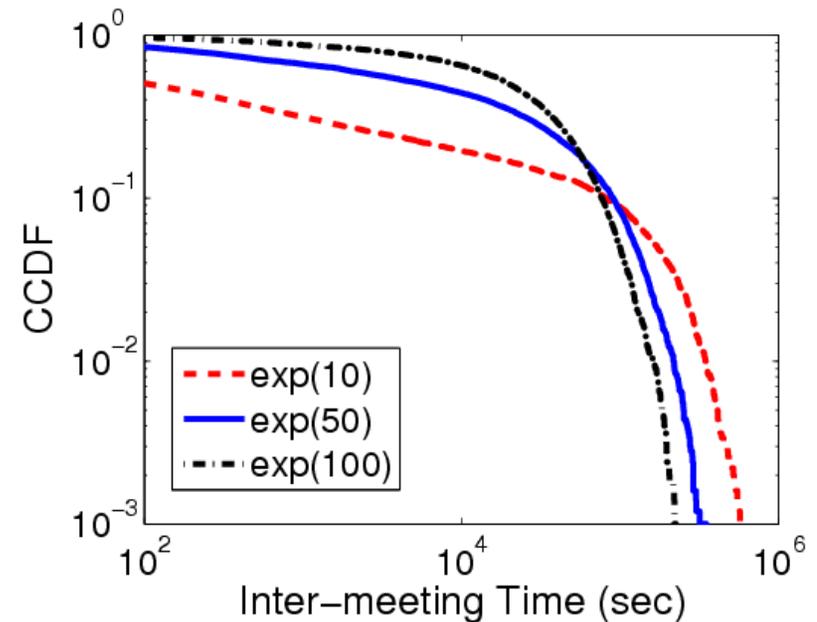
$$q = r = (1 - p)/3$$



Linear-Linear



Log-Log



■ 2-D CRW (200 x 200 grid)

- Correlation: simple RW (zero) → nearly go straight line (strong)
- Head of inter-meeting: light → heavy

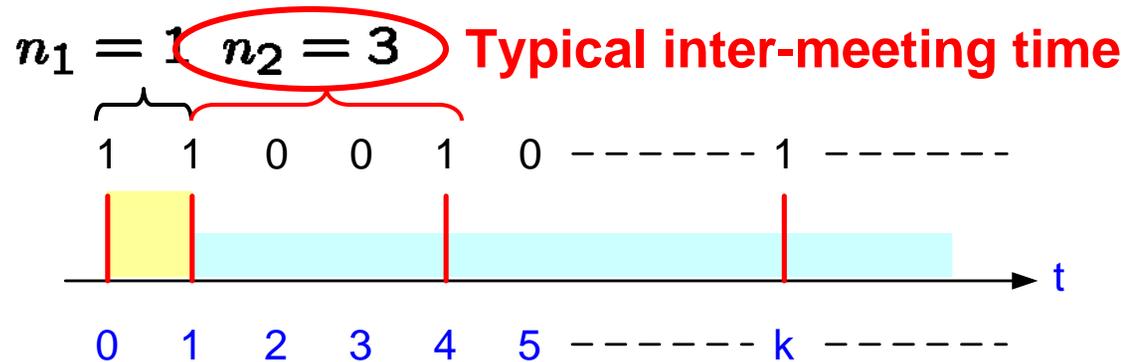


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Contact Indicator Process



- Contact Indicator process: $Y_t = \begin{cases} 0 & \text{out of contact} \\ 1 & \text{in contact} \end{cases}$
- Recurrence time $\{n_l\}_{l \geq 1}$ of state 1

$$T_1 \triangleq \min\{t \geq 0 : Y_t = 1\}, \quad T_k \triangleq \min\{t > T_{k-1} : Y_t = 1\} \quad (k \geq 2),$$

$$n_l \triangleq T_{l+1} - T_l.$$



Kac's Theorem for Ergodic Seq.

- **Kac's Theorems:** For a stationary 0–1 process $\{Y_t\}$ ($t = 0, 1, 2, \dots$) with ‘eventually-occurring’ state 1: **Expected time between two adjacent recurrences**

$$\mathbb{E}\{n_1 | Y_0 = 1\} = 1 / \mathbb{P}\{Y = 1\}, \quad (1)$$

$$\mathbb{E}\{n_1 | Y_0 = 1, Y_1 = 0\} = 1 + \frac{1 - \mathbb{P}\{Y = 1\}}{\mathbb{P}\{Y = 1\} - \mathbb{P}\{Y_0 = 1, Y_1 = 1\}}. \quad (2)$$

Expected time between two adjacent recurrences given Y_t first gets out of state 1

- Average recurrence time depends only on marginal distribution
 - Ergodic Markov Chain: well-known
 - General contact indicator process: stationary, but not MC !!
- Inter-meeting time: recurrence time getting out of “state 1” first
 - Short contact: (1) and (2) reduce to the same formula
 - V. Balakrishnan, G. Nicolis, and C. Nicolis, “Recurrence time statistics in deterministic and stochastic dynamical systems in continuous time: a comparison,” *Phys. Rev. E*, 61(3):2490–2499, Mar 2000.



Invariance Property of Contact Metrics

Theorem 5: The averages of T_H , T_I and T_C of CRW do not depend on $\rho \in (-1, 1)$. Specifically,

$$\mathbb{E}\{T_H\} = N - 1, \quad \mathbb{E}\{T_I\} = 2(N - 1), \quad \mathbb{E}\{T_C\} = 2.$$

Inter-hitting

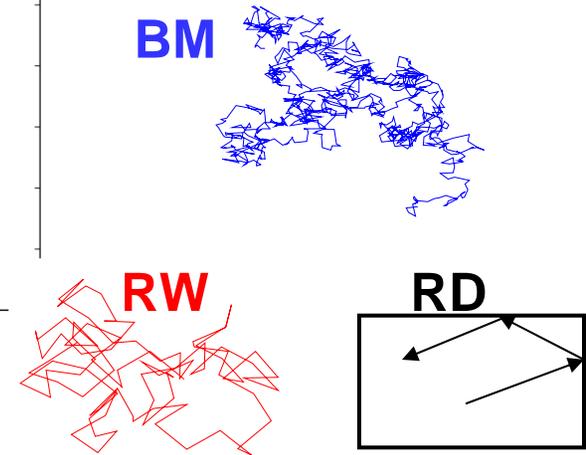
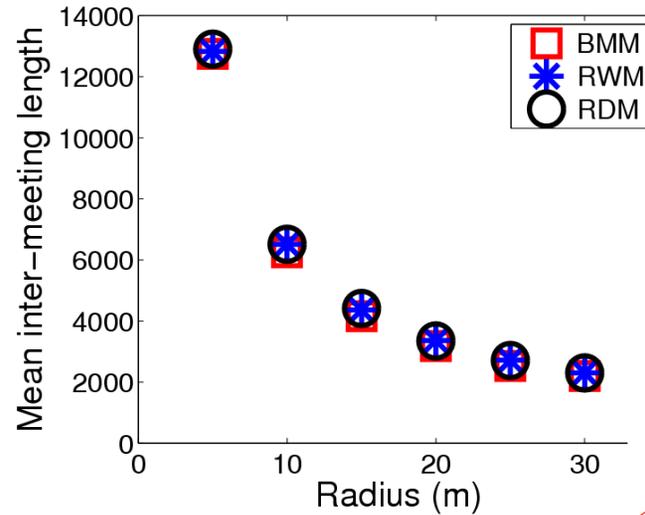
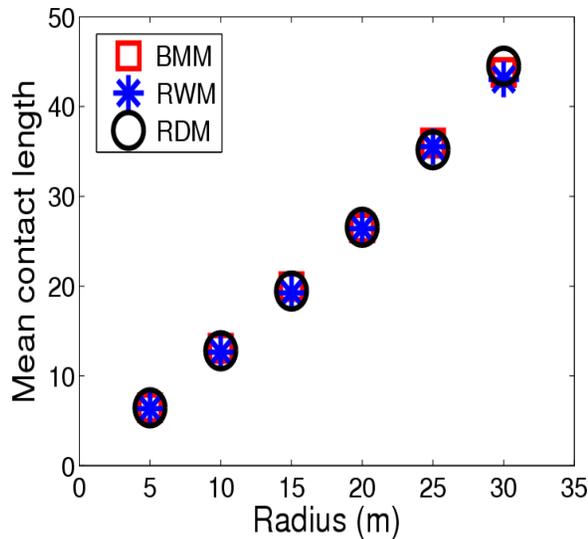
Inter-meeting

Contact

- Average contact-based metrics using 1-D simple RW model [1]
- We greatly extend the results in [1] into:
 - 2-D Correlated RW (CRW) model
 - General inter-contact to a set of nodes
 - Under both Boolean and SINR interference models
- [1] T. Karagiannis, J.-Y. Le Boudec, and M. Vojnovic, “Power law and exponential decay of inter contact times between mobile devices,” in *ACM MobiCom*, Montreal, Canada, Sept. 2007



Invariance Property of IRW Models



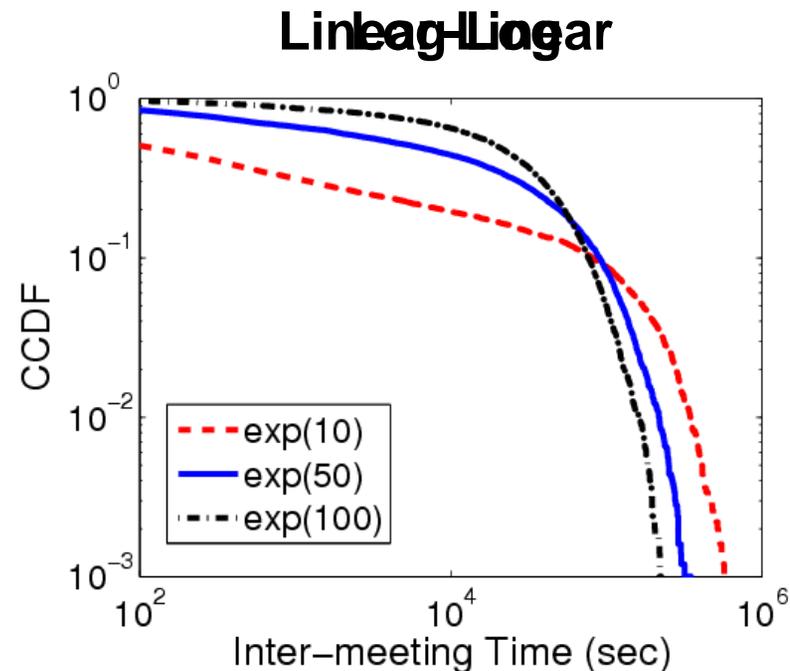
- Mean contact/inter-meeting time: invariant w.r.t. mobility model (step-length dist.)
 - Mobility model: BM (const: 8), RW (exp: 40), RD
 - Boolean interference model: 400m x 400m, $v = 1\text{m/s}$



Convex Ordering of Inter-meeting Time

■ Stronger correlation

- Heavier `head` of inter-meeting distribution
- Same average
- **Lighter `tail` to offset**
- Suggest a **convex ordering** relationship



$$T_{I1} \leq_{cx} T_{I2}, \text{ i.e., } \mathbb{E}\{\phi(T_{I1})\} \leq \mathbb{E}\{\phi(T_{I2})\} \quad (\forall \text{ convex } \phi(\cdot))$$

$$\text{In particular, } \mathbb{E}\{T_{I1}\} = \mathbb{E}\{T_{I2}\} \text{ and } \mathbb{E}\{T_{I1}^2\} \leq \mathbb{E}\{T_{I2}^2\}$$

- A. Muller and D. Stoyan, “Comparison Methods for Stochastic Models and Risks” John Wiley & Son, 2002



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- **Performance Implications and Outlook**



Mobility impacts performance...

■ **Well-known facts:**

- Different mobility models lead to different performances...
- Stationary distribution of mobile nodes under a given model
 - RWP, Random Walk (Brownian motion), Random Direction (RD), etc.

■ **“Poisson contact” assumption entitles you to**

- focus only on the “average” contact rate among mobile nodes
- differentiate performance in terms of densities of nodes (contact rates)
- proceed with Markovian analysis

■ **Invariance property is here !**

- “Average contact rate” does NOT depend on the step-length distributions of 2-D isotropic random walk (very general class)



Mobility impacts performance...

■ **Still, not so well-known:**

- **How** exactly does the mobility pattern impact the performance? In what sense?
- Lacks systematic way to predict performances over a given mobility pattern

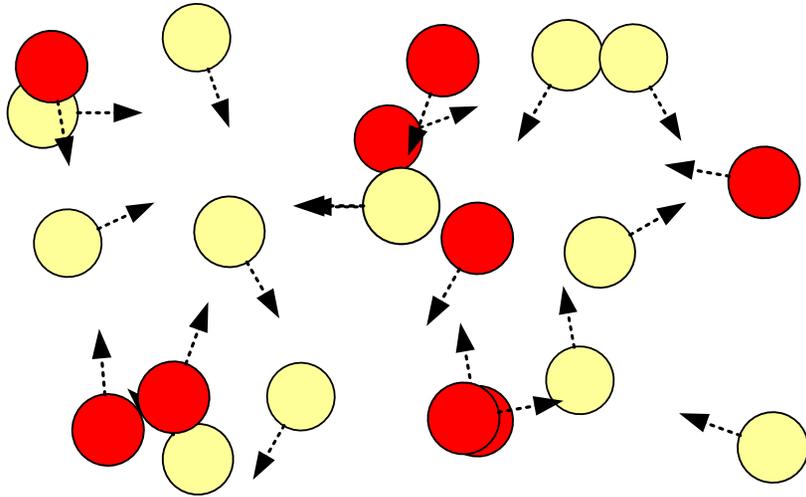
■ **Myth of Poisson Contact fails:**

- Inter-meeting (inter-contact) time among mobile node is far from being memoryless (instead, more of “dichotomic” type)

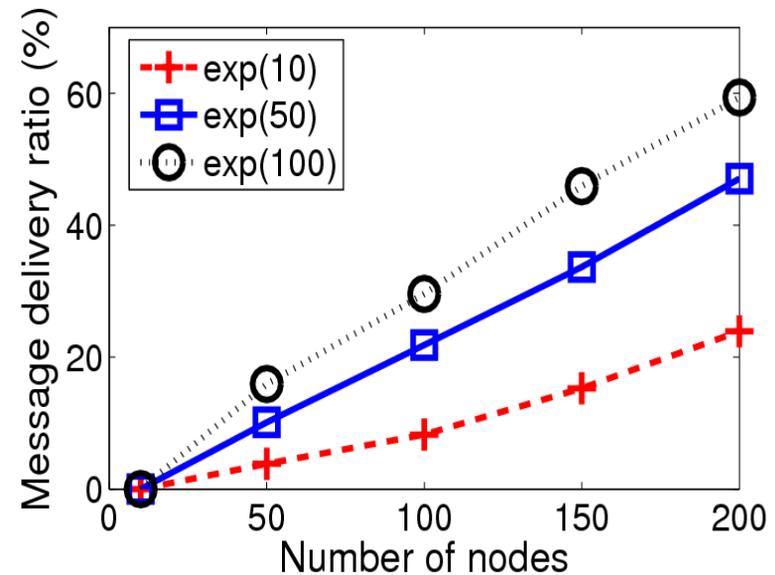
■ How does the **entire distribution of T_I** affect performance of a given protocol?



Motivating Example



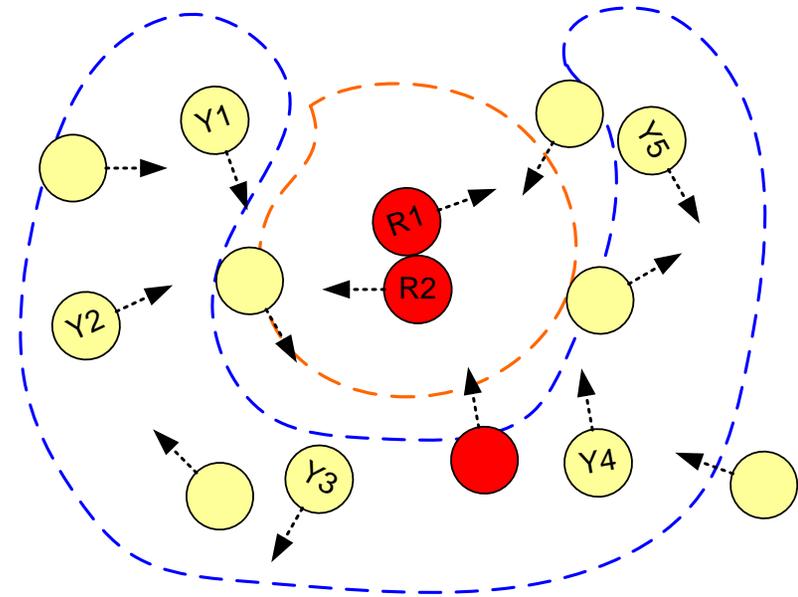
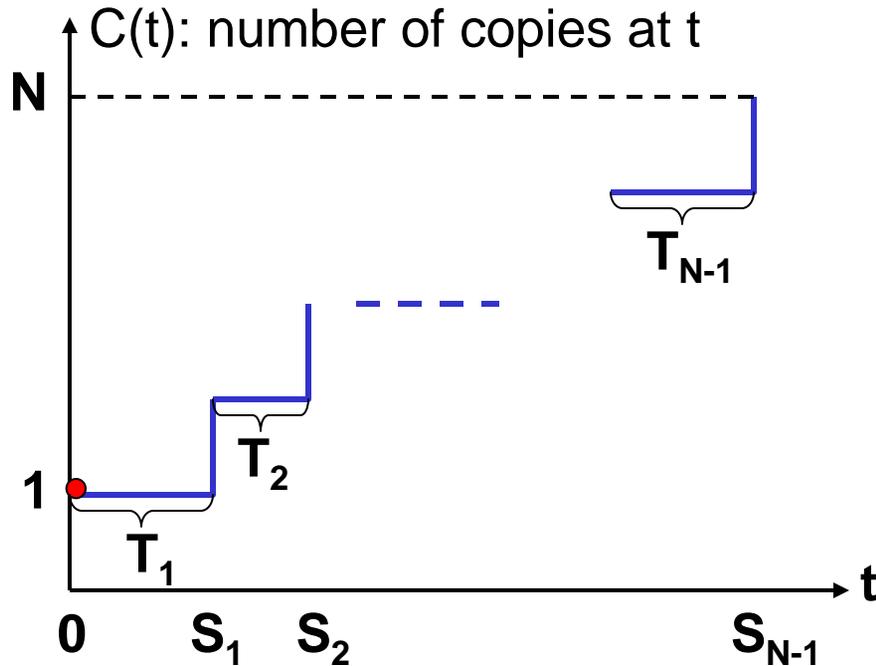
- Epidemic routing (ER) protocol
 - Similar to virus spreading



- Message delivery ratio under ER
- IRW with different step-length distributions
- **But they all have the same “average contact rates”!!**



Epidemic Forwarding/Routing and First Passage Time



Remaining inter-meeting time between $(R1, Y1), (R1, Y2), \dots, (R1, Y5)$
 $(R2, Y1), (R2, Y2), \dots, (R2, Y5)$

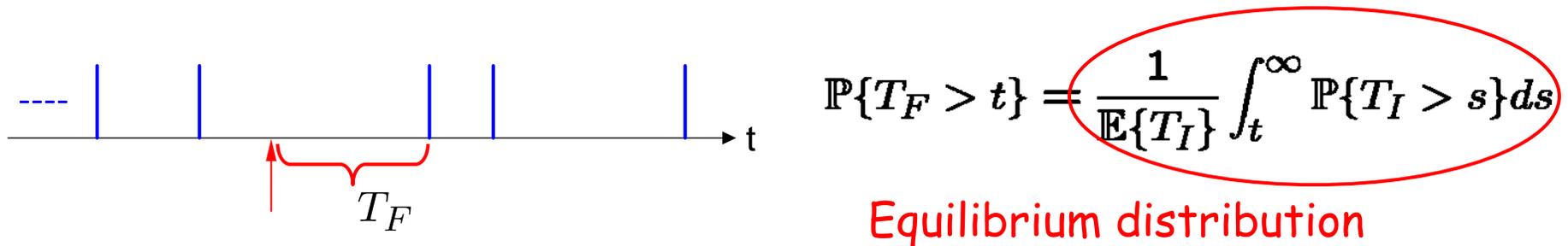
$$T_n = \inf\{t : C(t) = n+1\} - \inf\{t : C(t) = n\} = \min\{T_{n,1}^F, \dots, T_{n,n(N-n)}^F\}$$

Random observation time instance \rightarrow the First Passage Time (FPT)



Ordering of FPT

- Relationship with the inter-meeting time



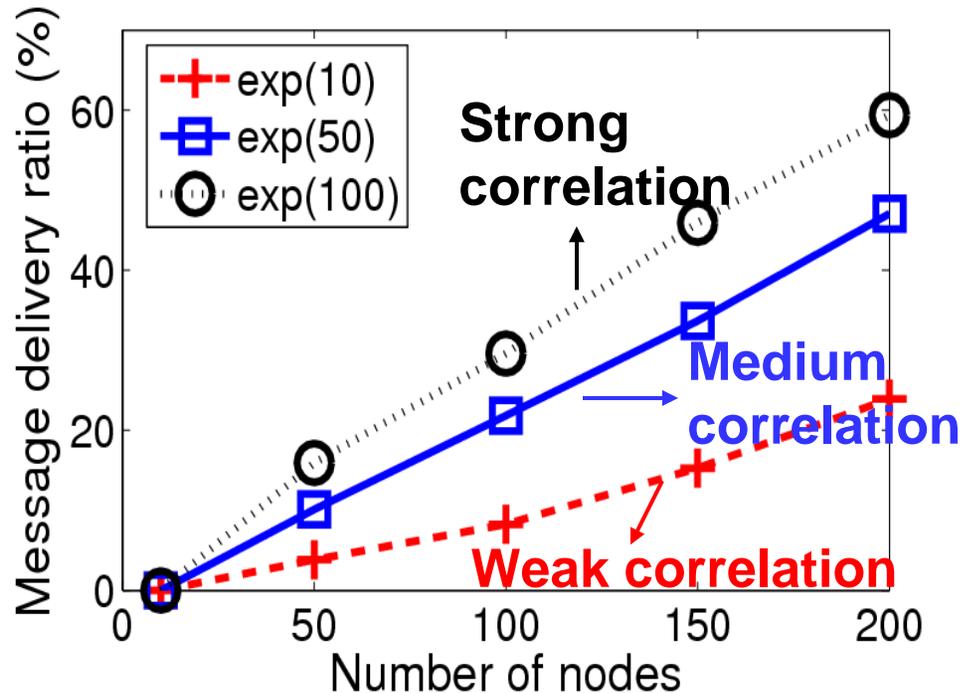
- Convex ordering of inter-meeting times: $T_{I1} \leq_{cx} T_{I2}$
- This implies stochastic ordering of FPTs

$$\mathbb{P}\{T_{F1} > t\} = \frac{\mathbb{E}\{[T_{I1} - t]^+\}}{\mathbb{E}\{T_{I1}\}} \leq \frac{\mathbb{E}\{[T_{I2} - t]^+\}}{\mathbb{E}\{T_{I2}\}} = \mathbb{P}\{T_{F2} > t\}$$

➤ In particular, $\mathbb{E}\{T_{F1}\} \leq \mathbb{E}\{T_{F2}\}$



Ordering of Performance via T_I , T_F



■ The same epidemic routing protocol

- Domain: 2000 x 2000 m
- Model: RW with exp(10), exp(50), exp(100)
- 1800 packets generated at the beginning
- Observe time instance: 6000 seconds

- Stronger correlation \rightarrow stochastically smaller T_F \rightarrow larger message delivery ratio



Summary & Outlook

- Our work is on stochastic analysis of mobility models, induced contact-based metrics, and ordering of network performance
 - Non-Poisson contact, “head” and “tail” of the inter-meeting time dist., time/space scaling with domain size
 - Convex ordering, invariance property for general mobility models with correlations
- Questions remain...
 - Other (more complicated) protocols over non-Poisson contacts?
 - Issues of delay, capacity (throughput), and cost (# of copies) under general mobility
 - Systematic design of better protocols/mobility toward high performance MANET in the face of non-Poisson contacts



Thank You!!

Questions & Answers